
EECE 321: Computer Organization

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Practice Problems

Arrays

Problem 1

- Compile the following code from C into MIPS
 - First do it assuming you can use pseudo-instructions
 - Then, replace pseudo-instructions with corresponding true MIPS instructions

```
# i:$s0, j:$s1, A:$s2
for(i=0; i<10; i++)
    for(j=0; j<=i; j++)
        A[i+16*j] = 13*A[i+j];
```

Problem 2

- Compiling arrays whose indices involve another memory reference
- Ex: Compile $A[B[4]]$
 - cannot be written in MIPS as $[4(16(\$s7))](\$s6)$
- First need to break it into pieces
 - Compile $j = B[4]$
 - Then compile $A[j]$
- Ex: Compile $A[B[j]]$
 - `sll $t0, $s2, 2` `# 4*j`
 - `add $t0, $t0, $s1` `# 4*j + base of B[]`
 - `lw $t0, 0($t0)` `# t0 = B[j]; note that B[j] is an index`
 - `sll $t0, $t0, 2` `# multiply index 'B[j]' by 4: 4*B[j]`
 - `add $t0, $t0, $s0` `# 4*B[j] + base of A[]`
 - `lw $t0, 0($t0)` `# load`
- Note: try to minimize as much as possible the number of temporary registers used
 - **Above we used only \$t0**

Problem 3: Clearing the Contents of an Array

- Compile the following C-function into MIPS:

```
clear (int array[], int size){
    int i;
    for(i=0;i<size;i++)
        array[i]=0;
}
```

- Choose your own variable-register mapping.

Problem 3 (cont'd): Clearing the Contents of an Array

```
clear (int array[], int size){
    int i;
    for(i=0;i<size;i++)
        array[i]=0;
}
```

```
# array:$a0, size:$a1, i:$t0

        li    $t0, 0
FOR:    slt   $t1, $t0, $a1
        beq   $t1, $0, EXIT
        sll   $t1, $t0, 2    # 4*i
        add   $t1, $t1, $a0
        sw    $0, 0($t1)
        addi  $t0, $t0, 1
        j     FOR
EXIT:   jr    $ra
```

Arithmetic/Overflow

Problem 4

- Suppose the instructions `slt`, `sltu`, `sli`, `sliu` were removed from the MIPS instruction set. Show how to perform `slt $s0,$s1,$s2` using the modified instruction set in which `slt` is not available (no pseudo-instructions allowed). Beware to account for overflow.
- **Solution:**

```
if ($s0<0) and ($s1>0) then
    $t0:=1
else if ($s0>0) and ($s1<0) then
    $t0:=0
else
    $t1:=$s0-$s1

    if ($t1<0) then
        $t0:=1
    else
        $t0:=0
```

Dissassembly

Problem 5

- Consider the following MIPS code:

```
addi $t1, $0, 100
loop: lw $s1, 0($s0)
      add $s2, $s2, $s1
      addi $s0, $s0, 4
      subi $t1, $t1, 1
      bne $t1, $0, loop
```

- Disassemble this code into C, and try to optimize it
- First trial:

```
// n : $t1; i: $s0; x : $s1; y:$s2
```

```
n = 100;
while (n != 0){
    x = A[i];
    y = y + x;
    n-- ;
}
```



```
i = 0;
while ( i < 100){
    y = y + A[i++];
}
```

Branches

Problem 6

- How to branch to a location that is further than what can be represented in the immediate field in a branch instruction?
 - Solution: Branch to a “jr” instruction
- Ex: if $\$s1 = \$s2$ jump to L, but L is very far away

```
    beq $s1 , $s2 , L1
    j L2
L1:  li $t0 , L    # here L is a 32-bit value that represents the 'far' address
    jr $t0
L2:
```
- What is the disadvantage of this approach? What needs to be changed if this code is moved in memory?

Problem 7

- Suppose that MIPS does not have conditional branch instructions (beq, bne, ...). Can you write a sequence of MIPS instructions to implement a conditional branch instruction?

Problem 8

- Translate the following switch statement in C into MIPS. Try to use as few registers as possible. Assume the following mapping: \$s1:x, \$s2:y, \$s3:z, \$s0:a. Add appropriate comments to your MIPS code.

```
switch(a){
    case 1: x = y + z;
    case 2: x = y - z;
    case -1: x = x - z;
    default: x = z + z;
}
```

```

                                addi $t0, $0, 1           # case a=1
                                addi $t1, $0, 2           # case a=2
                                addi $t2, $0, -1          # case a=-1
                                bne  $s0, $t0, L2         # handle case 1
                                add  $s1, $s2, $s3        #
                                j     EXIT
```

Solution:

```

L2:                                bne  $s0, $t1, L3         # handle case 2
                                sub  $s1, $s2, $s3
                                j     EXIT

L3:                                bne  $s0, $t2, D         # handle case -1
                                sub  $s1, $s1, $s3
                                j     EXIT

D:                                add  $s1, $s3, $s3
EXIT:
```

Problem 9

- Implement the instruction `max $t1,$t2,$t3` in MIPS, which returns the maximum of `$t2` and `$t3` in `$t1`, without using any conditional branch instructions (`beq`, `bne`). Also, you are not allowed to use pseudo-instructions.
- Solution:

```

                                add $t1,$t2,$0           # MAX is t2
                                jal MAX                 # $ra = address MAX

MAX:    slt $t0,$t3,$t2           # t0=1 if t2 is MAX, exit
        sll $t0,$t0,2            # t0 is 4
        addi $ra,$ra,20          # adjust jump offset
        add $ra,$ra,$t0
        jr $ra

T3MAX:  add $t1,$0,$t3           # t3 is MAX

T2MAX:  .....
```

Functions

Problem 10: Sorting Function

- Compile the following C-function into MIPS:

```
sort (int v[], int n){
    int i,j;
    for(i=0;i<n;i++){
        for(j=i-1;j>=0 && v[j]>v[j+1]; j--){
            swap(v,j);
        }
    }
}
```

```
swap (int v[], int k){
    int temp;
    temp=v[k];
    v[k]=v[k+1];
    v[k+1]=temp;
}
```

- Steps:
 - Allocate registers to program variables.
 - Produce code for the body of the function.
 - Preserve registers across the procedure invocation.
- Compiling swap: **#v:\$a0, k:\$a1**

```
swap:   sll    $t1,$a1,2           # $t1=k*4
        add    $t1,$a0,$t1       # $t1=v+4*k, $t1 has address of v[k]
        lw     $t0,0($t1)        # temp = v[k]
        lw     $t2,4($t1)       # $t2 = v[k+1]
        sw     $t2,0($t1)       # v[k] = $t2
        sw     $t0,4($t1)       # v[k+1] = temp
        jr     $ra              # return to caller
```

Problem 10 (cont'd): Compiling sort()

- First for loop: `#i:$s0, j:$s1, n:$a1`

```
sort (int v[], int n){
    int i,j;
    for(i=0;i<n;i++){
        for(j=i-1;j>=0 && v[j]>v[j+1]; j--){
            swap(v,j);
        }
    }
}
```

```
FOR1:    add    $s0,$zero,$zero        # i=0
         slt    $t0,$s0,$a1         # if i>=n
         beq    $t0,$zero,EXIT1     # exit loop
         . . .
         (body of first loop)
         . . .
         addi   $s0,$s0,1           # i++
         j     FOR1
EXIT1:
```

Problem 10 (cont'd): Compiling sort()

```
sort (int v[], int n){
    int i,j;
    for(i=0;i<n;i++){
        for(j=i-1;j>=0 && v[j]>v[j+1]; j--){
            swap(v,j);
        }
    }
}
```

- Second for loop: #i:s0, j:\$s1

```
FOR2:    addi    $s1,$s0,-1          # j=i-1
         slti    $t0,$s1,0        # $t0=1 if j<0
         bne    $t0,$zero,EXIT2   # exit loop if j<0
         sll    $t1,$t1,2         # $t1 = 4*j
         add    $t2,$a0,$t1       # $t2 = v + 4*j
         lw     $t3,0($t2)        # $t3 = v[j]
         lw     $t4,4($t2)        # $t4 = v[j+1]
         slt    $t0,$t4,$t3       # $t0=0 if $t4 >= $t3
         beq   $t0,$zero,EXIT2   # goto EXIT2 if $t4 >= $t3
         . . .
         (body of second loop)
         . . .
         addi   $s1,$s1,1         # j--
         j     FOR2
EXIT2:
```

Problem 10 (cont'd): Compiling sort()

- Preserving registers:

- Need to save \$a0, \$a1. Can do so on stack, but better copy them to unused registers \$s2,\$s3.

```
add  $s2,$a0,$zero    # move $a0 into $s2
add  $s3,$a1,$zero    # move $a1 into $s3
```

- Pass parameters to swap as:

```
add  $a0,$s2,$zero    # first swap parameter is v
add  $a1,$s1,$zero    # second swap parameter is j
```

- Since sort uses saved registers, it must save them on stack in addition to \$ra:

```
addi  $sp,$sp,-20      # make room for 5 registers
sw    $ra,16($sp)     # save $ra
sw    $s3,12($sp)     # save $s3
sw    $s2, 8($sp)     # save $s2
sw    $s1, 4($sp)     # save $s1
sw    $s0, 0($sp)     # save $s0
```

- Epilogue simply pops the stack.
- See the overall code in your textbook.