

Problem 1-

SOLUTION

We draw radial lines from the center to the tangent points A and B , as shown in Figure 2.11. The radial lines O_1A and O_2B must be perpendicular to the belt AB , hence both lines are parallel and at the same angle θ with the horizontal. We can draw a line parallel to AB through point O_2 to get line CO_2 . Noting that CA is equal to O_2B , we can obtain CO_1 as the difference between the two radii.

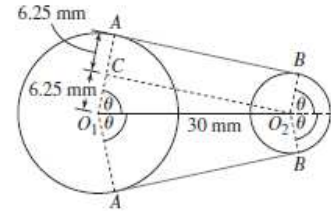


Figure 2.11 Analysis of geometry.

Triangle O_1CO_2 in Figure 2.11 is a right triangle, so we can find side CO_2 and the angle θ as:

$$AB = CO_2 = \sqrt{(30 \text{ mm})^2 - (6.25 \text{ mm})^2} = 29.342 \text{ mm} \quad (\text{E1})$$

$$\cos \theta = \frac{CO_1}{O_1O_2} = \frac{6.25 \text{ mm}}{30 \text{ mm}} \quad \text{or} \quad \theta = \cos^{-1}(0.2083) = 1.3609 \text{ rad} \quad (\text{E2})$$

The deformed length L_f of the belt is the sum of arcs AA and BB and twice the length AB :

$$AA = (12.5 \text{ mm})(2\pi - 2\theta) = 44.517 \text{ mm} \quad (\text{E3})$$

$$BB = (6.25 \text{ mm})(2\pi - 2\theta) = 22.258 \text{ mm} \quad (\text{E4})$$

$$L_f = 2(AB) + AA + BB = 125.46 \text{ mm} \quad (\text{E5})$$

We are given that $0.019 \leq \varepsilon \leq 0.034$. From Equation (2.1) we obtain the limits on the original length:

$$\varepsilon = \frac{L_f - L_0}{L_0} \leq 0.034 \quad \text{or} \quad L_0 \geq \frac{125.46}{1 + 0.034} \text{ mm} \quad \text{or} \quad L_0 \geq 121.33 \text{ mm} \quad (\text{E6})$$

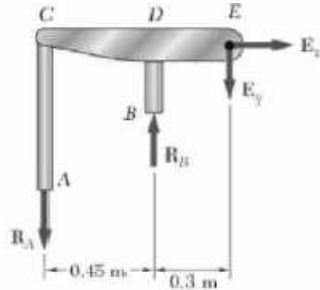
$$\varepsilon = \frac{L_f - L_0}{L_0} \geq 0.019 \quad \text{or} \quad L_0 \leq \frac{125.46}{1 + 0.019} \text{ mm} \quad \text{or} \quad L_0 \leq 123.1 \text{ mm} \quad (\text{E7})$$

To satisfy Equations (E6) and (E7) to the nearest millimeter, we obtain the following limits on the original length L_0 :

$$\text{ANS.} \quad 122 \text{ mm} \leq L_0 \leq 123 \text{ mm}$$

Problem 2- part 1

SOLUTION



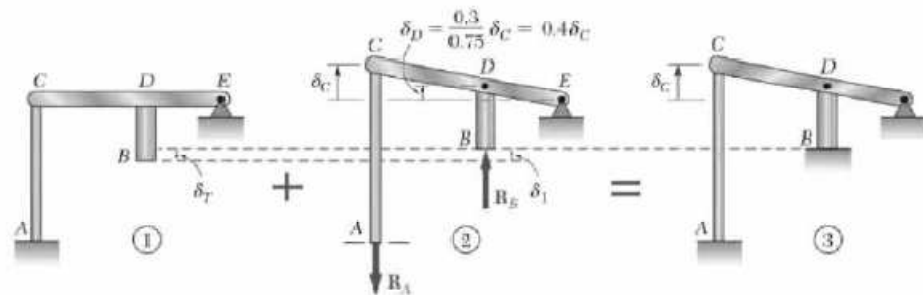
Statics. Considering the free body of the entire assembly, we write

$$+\uparrow \Sigma M_E = 0: R_A(0.75 \text{ m}) - R_B(0.3 \text{ m}) = 0 \quad R_A = 0.4R_B \quad (1)$$

Deformations. We use the method of superposition, considering R_B as redundant. With the support at B removed, the temperature rise of the cylinder causes point B to move down through δ_T . The reaction R_B must cause a deflection δ_1 equal to δ_T so that the final deflection of B will be zero (Fig. 3).

Deflection δ_T . Because of a temperature rise of $50^\circ - 20^\circ = 30^\circ\text{C}$, the length of the brass cylinder increases by δ_T .

$$\delta_T = L(\Delta T)\alpha = (0.3 \text{ m})(30^\circ\text{C})(20.9 \times 10^{-6}/^\circ\text{C}) = 188.1 \times 10^{-6} \text{ m} \downarrow$$



Deflection δ_1 . We note that $\delta_D = 0.4\delta_C$ and $\delta_1 = \delta_D + \delta_{B/D}$.

$$\delta_C = \frac{R_A L}{AE} = \frac{R_A(0.9 \text{ m})}{\frac{1}{4}\pi(0.022 \text{ m})^2(200 \text{ GPa})} = 11.84 \times 10^{-9} R_A \uparrow$$

$$\delta_D = 0.40\delta_C = 0.4(11.84 \times 10^{-9} R_A) = 4.74 \times 10^{-9} R_A \uparrow$$

$$\delta_{B/D} = \frac{R_B L}{AE} = \frac{R_B(0.3 \text{ m})}{\frac{1}{4}\pi(0.03 \text{ m})^2(105 \text{ GPa})} = 4.04 \times 10^{-9} R_B \uparrow$$

We recall from (1) that $R_A = 0.4R_B$ and write

$$\delta_1 = \delta_D + \delta_{B/D} = [4.74(0.4R_B) + 4.04R_B]10^{-9} = 5.94 \times 10^{-9} R_B \uparrow$$

But $\delta_T = \delta_1$: $188.1 \times 10^{-6} \text{ m} = 5.94 \times 10^{-9} R_B \quad R_B = 31.7 \text{ kN}$

Stress in Cylinder: $\sigma_B = \frac{R_B}{A} = \frac{31.7 \text{ kN}}{\frac{1}{4}\pi(0.03)^2} \quad \sigma_B = 44.8 \text{ MPa} \leftarrow$

Problem 2-Part 2

A 60-mm cube is made from layers of graphite epoxy with fibers aligned in the x direction. The cube is subjected to a compressive load of 140 kN in the x direction. The properties of the composite material are: $E_x = 155.0$ GPa, $E_y = 12.10$ GPa, $E_z = 12.10$ GPa, $\nu_{xy} = 0.248$, $\nu_{xz} = 0.248$, and $\nu_{yz} = 0.458$. Determine the changes in the cube dimensions, knowing that (a) the cube is free to expand in the y and z directions (Fig. 2.56); (b) the cube is free to expand in the z direction, but is restrained from expanding in the y direction by two fixed frictionless plates (Fig. 2.57).

(a) **Free in y and z Directions.** We first determine the stress σ_x in the direction of loading. We have

$$\sigma_x = \frac{P}{A} = \frac{-140 \times 10^3 \text{ N}}{(0.060 \text{ m})(0.060 \text{ m})} = -38.89 \text{ MPa}$$

Since the cube is not loaded or restrained in the y and z directions, we have $\sigma_y = \sigma_z = 0$. Thus, the right-hand members of Eqs. (2.45) reduce to their first terms. Substituting the given data into these equations, we write

$$\begin{aligned}\epsilon_x &= \frac{\sigma_x}{E_x} = \frac{-38.89 \text{ MPa}}{155.0 \text{ GPa}} = -250.9 \times 10^{-6} \\ \epsilon_y &= -\frac{\nu_{xy}\sigma_x}{E_y} = -\frac{(0.248)(-38.89 \text{ MPa})}{155.0 \text{ GPa}} = +62.22 \times 10^{-6} \\ \epsilon_z &= -\frac{\nu_{xz}\sigma_x}{E_z} = -\frac{(0.248)(-38.89 \text{ MPa})}{155.0 \text{ GPa}} = +62.22 \times 10^{-6}\end{aligned}$$

The changes in the cube dimensions are obtained by multiplying the corresponding strains by the length $L = 0.060$ m of the side of the cube:

$$\begin{aligned}\delta_x &= \epsilon_x L = (-250.9 \times 10^{-6})(0.060 \text{ m}) = -15.05 \mu\text{m} \\ \delta_y &= \epsilon_y L = (+62.2 \times 10^{-6})(0.060 \text{ m}) = +3.73 \mu\text{m} \\ \delta_z &= \epsilon_z L = (+62.2 \times 10^{-6})(0.060 \text{ m}) = +3.73 \mu\text{m}\end{aligned}$$

(b) **Free in z Direction, Restrained in y Direction.** The stress in the x direction is the same as in part a, namely, $\sigma_x = -38.89$ MPa. Since the cube is free to expand in the z direction as in part a, we again have $\sigma_z = 0$. But since the cube is now restrained in the y direction, we should expect a stress σ_y different from zero. On the other hand, since the cube cannot expand in the y direction, we must have $\delta_y = 0$ and, thus, $\epsilon_y = \delta_y/L = 0$. Making $\sigma_z = 0$ and $\epsilon_y = 0$ in the second of Eqs. (2.45), solving that equation for σ_y , and substituting the given data, we have

$$\begin{aligned}\sigma_y &= \left(\frac{E_y}{E_x}\right)\nu_{xy}\sigma_x = \left(\frac{12.10}{155.0}\right)(0.248)(-38.89 \text{ MPa}) \\ &= -752.9 \text{ kPa}\end{aligned}$$

Now that the three components of stress have been determined, we can use the first and last of Eqs. (2.45) to compute the strain components ϵ_x and ϵ_z . But the first of these equations contains

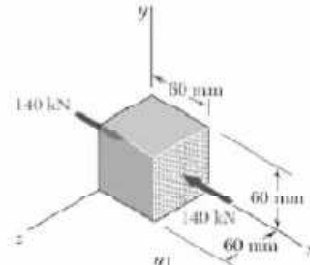


Fig. 2.56

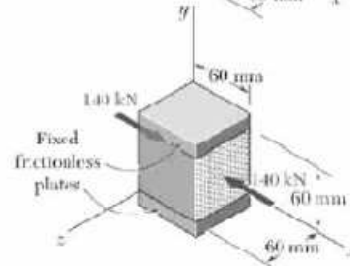


Fig. 2.57

Poisson's ratio ν_{yz} , and, as we saw earlier, this ratio is not equal to the ratio ν_{xy} , which was among the given data. To find ν_{yz} we use the first of Eqs. (2.46) and write

$$\nu_{yz} = \left(\frac{E_y}{E_z}\right)\nu_{xy} = \left(\frac{12.10}{155.0}\right)(0.248) = 0.01936$$

Making $\sigma_z = 0$ in the first and third of Eqs. (2.45) and substituting in these equations the given values of E_x , E_y , ν_{xy} , and ν_{yz} , as well as the values obtained for σ_x , σ_y , and ν_{xy} , we have

$$\begin{aligned}\epsilon_x &= \frac{\sigma_x}{E_x} - \frac{\nu_{yz}\sigma_y}{E_z} = \frac{-38.89 \text{ MPa}}{155.0 \text{ GPa}} - \frac{(0.01936)(-752.9 \text{ kPa})}{12.10 \text{ GPa}} = -249.7 \times 10^{-6} \\ \epsilon_z &= -\frac{\nu_{xz}\sigma_x}{E_z} - \frac{\nu_{yz}\sigma_y}{E_y} = -\frac{(0.248)(-38.89 \text{ MPa})}{155.0 \text{ GPa}} - \frac{(0.458)(-752.9 \text{ kPa})}{12.10 \text{ GPa}} = +90.72 \times 10^{-6}\end{aligned}$$

The changes in the cube dimensions are obtained by multiplying the corresponding strains by the length $L = 0.060$ m of the side of the cube:

$$\begin{aligned}\delta_x &= \epsilon_x L = (-249.7 \times 10^{-6})(0.060 \text{ m}) = -14.98 \mu\text{m} \\ \delta_y &= \epsilon_y L = (0)(0.060 \text{ m}) = 0 \\ \delta_z &= \epsilon_z L = (+90.72 \times 10^{-6})(0.060 \text{ m}) = +5.44 \mu\text{m}\end{aligned}$$

Comparing the results of parts a and b, we note that the difference between the values obtained for the deformation δ_x in the direction of the fibers is negligible. However, the difference between the values obtained for the lateral deformation δ_z is not negligible. This deformation is clearly larger when the cube is restrained from deforming in the y direction.

Problem 3

Equilibrium Condition: $\sigma_x = a + by + cz$

$$0 = \int_A \sigma_x dA$$

$$0 = \int_A (a + by + cz) dA$$

$$0 = a \int_A dA + b \int_A y dA + c \int_A z dA \quad [1]$$

$$M_y = \int_A z \sigma_x dA$$

$$= \int_A z(a + by + cz) dA$$

$$= a \int_A z dA + b \int_A yz dA + c \int_A z^2 dA \quad [2]$$

$$M_z = \int_A -y \sigma_x dA$$

$$= \int_A -y(a + by + cz) dA$$

$$= -a \int_A y dA - b \int_A y^2 dA - c \int_A yz dA \quad [3]$$

Section Properties: The integrals are defined in Appendix A. Note that

$$\int_A y dA = \int_A z dA = 0. \text{ Thus,}$$

From Eq. [1] $Aa = 0$

From Eq. [2] $M_y = bI_{yz} + cI_y$

From Eq. [3] $M_z = -bI_z - cI_{yz}$

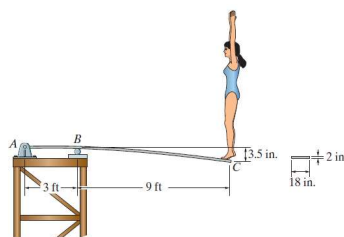
Solving for a, b, c :

$$a = 0 \text{ (Since } A \neq 0)$$

$$b = -\left(\frac{M_z I_y + M_y I_{yz}}{I_y I_z - I_{yz}^2}\right) \quad c = \frac{M_y I_z + M_z I_{yz}}{I_y I_z - I_{yz}^2}$$

Thus, $\sigma_x = -\left(\frac{M_z I_y + M_y I_{yz}}{I_y I_z - I_{yz}^2}\right)y + \left(\frac{M_y I_z + M_z I_{yz}}{I_y I_z - I_{yz}^2}\right)z \quad \text{(Q.E.D.)}$

Problem 4



Support Reactions and Elastic Curve. As shown in Fig. *a*.

Moment Functions. Referring to the free-body diagrams of the diving board's cut segments, Fig. *b*, $M(x_1)$ is

$$\zeta + \sum M_O = 0; \quad M(x_1) + 3Wx_1 = 0 \quad M(x_1) = -3Wx_1$$

and $M(x_2)$ is

$$\zeta + \sum M_O = 0; \quad -M(x_2) - Wx_2 = 0 \quad M(x_2) = -Wx_2$$

Equations of Slope and Elastic Curve.

$$EI \frac{d^2v}{dx^2} = M(x)$$

For coordinate x_1 ,

$$EI \frac{d^2v_1}{dx_1^2} = -3Wx_1$$

$$EI \frac{dv_1}{dx_1} = -\frac{3}{2}Wx_1^2 + C_1 \quad (1)$$

$$EIv_1 = -\frac{1}{2}Wx_1^3 + C_1x_1 + C_2 \quad (2)$$

For coordinate x_2

$$EI \frac{d^2v_2}{dx_2^2} = -Wx_2$$

$$EI \frac{dv_2}{dx_2} = -\frac{1}{2}Wx_2^2 + C_3 \quad (3)$$

$$EIv_2 = -\frac{1}{6}Wx_2^3 + C_3x_2 + C_4 \quad (4)$$

Boundary Conditions. At $x_1 = 0$, $v_1 = 0$. Then, Eq. (2) gives

$$EI(0) = -\frac{1}{2}W(0^3) + C_1(0) + C_2 \quad C_2 = 0$$

At $x_1 = 3$ ft, $v_1 = 0$. Then, Eq. (2) gives

$$EI(0) = -\frac{1}{2}W(3^3) + C_1(3) + 0 \quad C_1 = 4.5W$$

At $x_2 = 9$ ft, $v_2 = 0$. Then, Eq. (4) gives

$$EI(0) = -\frac{1}{6}W(9^3) + C_3(9) + C_4$$

$$9C_3 + C_4 = 121.5W \quad (5)$$

Continuity Conditions. At $x_1 = 3$ ft and $x_2 = 9$ ft, $\frac{dv_1}{dx_1} = \frac{dv_2}{dx_2}$. Thus, Eqs. (1) and (3) give

$$\frac{3}{2}W(3^2) + 4.5W = \left[\frac{1}{2}W(9^2) + C_3 \right] \quad C_3 = 49.5W$$

Substituting the value of C_3 into Eq. (5),

$$C_4 = -324W$$

Substituting the values of C_3 and C_4 into Eq. (4),

$$v_2 = \frac{1}{EI} \left(-\frac{1}{6}Wx_2^3 + 49.5Wx_2 - 324W \right)$$

At $x_2 = 0$, $v_2 = -3.5$ in. Then,

$$-3.5 = \frac{-324W(1728)}{1.5(10^6) \left[\frac{1}{12}(18)(2^3) \right]}$$

$$W = 112.53 \text{ lb} = 113 \text{ lb}$$

Ans.

