

MECH 430 Instrumentation & Measurement

<u>Question 1</u>

A rotary variable differential transformer has a specification which includes the following information:

Ranges:	\pm 30°, linearity error \pm 0.5% full range
	\pm 60°, linearity error \pm 2.0% full range
Sensitivity:	1.1 (mV/V input)/degree
Impedance:	Primary 750 Ω , Secondary 2000 Ω
What will be	-
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(a) The error in a reading of 40° due to nonlinearity when the RVDT is used on the $\pm 60^{\circ}$ range?

The error in Reading is: (2.0/100)*120=2.4°

(b) The output voltage change that occurs per degree if there is an input voltage of 3V?

1.1 (mV/V input) * 3 (V input) = **3.3** V/degree

(c) The resolution of the RVDT if the input voltage is 5V if the reading instrument has a resolution of 0.1 mV?

Based on the 5V input, the sensitivity is 5.5 V/degree, for every 0.1 mV, the resolution is: 0.018182°.

Question 2

What are the desirable sensor characteristics for:

- Sensitivity: Large AND Constant
- Nonlinearity: Zero (nonexistent)
- Full Scale: Large or Infinite
- Zero Drift: Zero (nonexistent)
- Bandwidth: Large or Infinite