

AMERICAN UNIVERSITY OF BEIRUT
 FACULTY OF ENGINEERING AND ARCHITECTURE
 EECE 460 Control Systems
 Spring 2006-2007

Quiz II Solution

Problem 1 (60 points):

a) There is a pole at $\omega = 0$ and at $\omega = 0.3 \rightarrow G(s)$ is of the form $\frac{K}{s(1 + \frac{s}{0.3})}$.

At $\omega = 10^{-2}$ $G(s)$ should be 48 dB (from figure) $\rightarrow K$ contributes to 8 dB or $K = 2.52$.

Thus $G(s) = \frac{2.52}{s(1 + \frac{s}{0.3})} \rightarrow G(s) = \frac{0.756}{s(s + 0.3)}$

b) Pole at $\omega = 0 \rightarrow$ marginally stable

c) $K_v = \lim_{s \rightarrow 0} s G(s) = 2.52$

d) $G_M = \infty, P_M = 19.5^\circ$

e) $G_M > 0, P_M > 0$ and min. phase OLTF \rightarrow stable CLTF

f) Choose the lead compensator: The maximum phase margin that a lead compensator can contribute is 65° . The phase margin of the uncompensated system is 19.5° and thus the lead compensator should contribute around $35^\circ (=25 + 10)$ which is beyond the allowable range.

g) The lead compensator is of the form: $K \frac{Ts + 1}{\alpha Ts + 1}$ where $K = K_C \alpha$

$\Phi_m = 35^\circ \rightarrow \alpha = 0.27$

The static error velocity should remain the same: $K_v = 2.52$

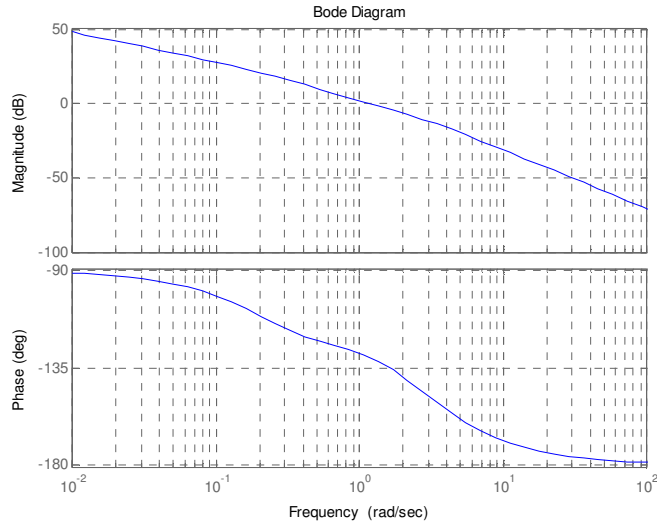
$\rightarrow \lim_{s \rightarrow 0} s \frac{0.756}{s(s + 0.3)} K \frac{Ts + 1}{\alpha Ts + 1} = 2.52 \rightarrow K = 1 \rightarrow K_c = 1/\alpha = 3.7$

$-20 \log \left(\frac{1}{\sqrt{\alpha}} \right) = -5.6 \rightarrow$ The gain cross over frequency, $\omega_c \approx 1.2$

$\rightarrow \omega_1 = \frac{1}{T} = \sqrt{\alpha} \omega_c = 0.62$ and $\omega_2 = \frac{1}{\alpha T} = \frac{\omega_c}{\sqrt{\alpha}} = 2.31$ rd/s

$\rightarrow G_c(s) = \frac{1.6s + 1}{0.43s + 1} \rightarrow$ O.L.T.F = $G(s) G_c(s) = \frac{1.6s + 1}{0.43s + 1} \frac{0.756}{s(s + 0.3)}$

The bode diagram of the compensated system is shown below. The new G_M and P_M are ∞ and 49.5° , respectively.



Problem 2 (60 points):

a) S-plane poles: 0, -4

S-plane zeros: +2i, -2i

→ The system is marginally stable

b) $K \rightarrow 0$, Therefore C.L.T.F poles = O.L.T.F poles = 0, -4

c) Range of pure real poles of C.L.T.F = [-4, 0]

d) System critically damped → $\zeta = 1$. The C.L.T.F = $\frac{KG}{1+KG} =$

$$\frac{K(s^2 + 4)}{(1+K)s^2 + 4s + 4K} = \frac{\left(\frac{K}{1+K}\right)(s^2 + 4)}{s^2 + \left(\frac{4}{1+K}\right)s + \left(\frac{4K}{1+K}\right)}$$

$$\rightarrow 2\omega_n = \left(\frac{4}{1+K}\right) \text{ and } \omega_n^2 = \left(\frac{4K}{1+K}\right) \rightarrow K = 0.618$$

e) The C.L.T.F poles converge to the O.L.T.F zeros = +2i and -2i

f) $0.618 < K < \infty$

g)

