

Problem Set 4 Solution: Viscous Flow

“Advanced Fluid Mechanics Problems” by Shapiro and Sonin
 Problems 6.1, 6.3, 6.7, 6.10, 6.16, 6.20, 6.21.

Problem 6.1

Refer to Figure 1 for the schematic. The flow is steady.

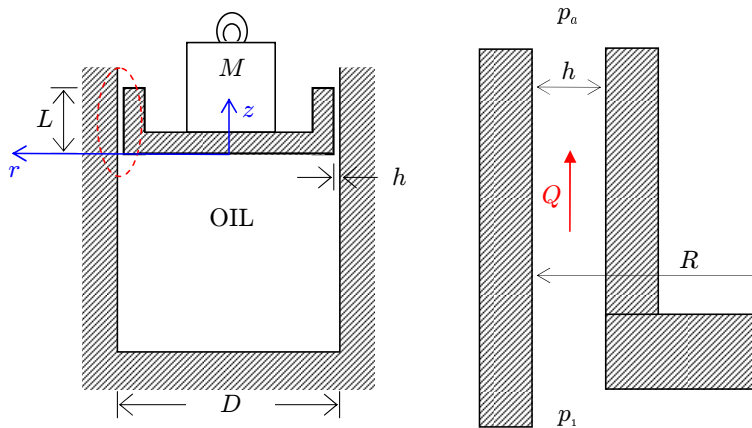


Figure 1: Schematic of Problem 6.1

(a) We assume that the flow is steady and fully developed in the channel between the piston and cylinder. The z -component of the momentum equation is

$$0 = -\frac{\partial p}{\partial z} + \mu \left(\frac{\partial^2 u}{\partial r^2} + \frac{1}{r} \frac{\partial u}{\partial r} \right)$$

where gravity is neglected. We can neglect the term $\frac{1}{r} \frac{\partial u}{\partial r}$ because

$$\frac{\frac{1}{r} \frac{\partial u}{\partial r}}{\frac{\partial^2 u}{\partial r^2}} \simeq \frac{h}{R} \ll 1$$

where $R = D/2$. From the momentum conservation in the r -direction, we can show that

$$\frac{\partial p}{\partial r} \simeq 0 \Rightarrow p = p(z) \text{ and } \frac{\partial p}{\partial z} = \frac{dp}{dz}$$

Therefore equation (1) reduces to

$$\frac{\partial^2 u}{\partial r^2} = \frac{1}{\mu} \frac{dp}{dz}$$

subject to the boundary conditions

$$\begin{aligned} u &= 0 \text{ at } r = R - h \\ u &= 0 \text{ at } r = R \end{aligned}$$

The velocity is then given by

$$u(r) = \frac{1}{2\mu} \frac{dp}{dz} \left(r^2 - (2R - h)r + R(R - h) \right)$$

The volume flow rate is then given by

$$\begin{aligned} Q &= 2\pi \left(R - \frac{h}{2} \right) \int_{R-h}^h u(r) dr \\ &= -2\pi \left(R - \frac{h}{2} \right) \frac{h^3}{12\mu} \frac{dp}{dz} \end{aligned}$$

We conclude from the last equation that dp/dz is constant,

$$\frac{dp}{dz} = -\frac{p_1 - p_a}{L} = -\frac{Mg}{\pi R^2 L}$$

where the shear force on the piston acting vertically upwards has been neglected. The leakage volume flow rate is finally given as

$$Q = \frac{Mgh^3}{6\mu R^2 L} \left(R - \frac{h}{2} \right) \simeq \frac{Mgh^3}{6\mu RL}$$

Problem 6.3

Refer to Figure 2 for the schematic. The flow is steady.

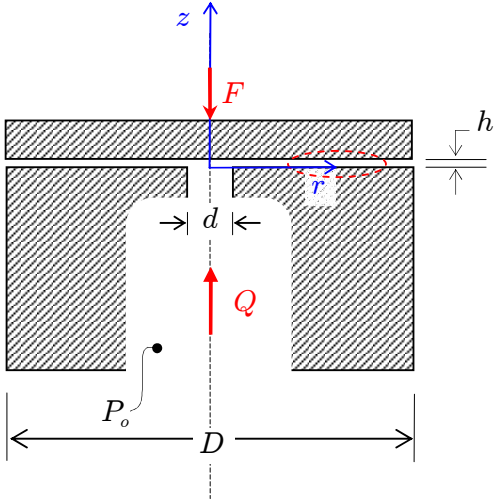


Figure 2: Schematic of Problem 6.3

(a) We assume that the flow is steady and fully developed in the channel between the upper and lower plates away from the center, i.e. for $r > d/2$. The momentum equation in the r -direction is

$$\rho \left(u \frac{\partial u}{\partial r} + w \frac{\partial u}{\partial z} \right) = - \frac{\partial p}{\partial r} + \mu \left(\frac{\partial^2 u}{\partial r^2} + \frac{1}{r} \frac{\partial u}{\partial r} - \frac{u}{r^2} + \frac{\partial^2 u}{\partial z^2} \right)$$

The ratio of the dominant inertia term to the dominant diffusion term is

$$\frac{\rho u \frac{\partial u}{\partial r}}{\mu \frac{\partial^2 u}{\partial z^2}} \simeq \frac{\rho \frac{\bar{u}^2}{r}}{\mu \frac{\bar{u}}{h^2}} = \frac{\rho \bar{u} h}{\mu r} = \text{Re}_h \frac{h}{r}$$

(b) Noting that $Q = 2\pi r h \bar{u}$, the flow may be assumed to be inertia free if

$$\begin{aligned} \frac{\rho \bar{u} h}{\mu r} &\ll 1 \\ \Rightarrow \frac{Q}{2\pi r h} \frac{\rho h}{\mu r} &\ll 1 \\ \Rightarrow r^2 &\gg \frac{\rho Q h}{2\pi \mu} \\ \Rightarrow \sqrt{\frac{\rho Q h}{2\pi \mu}} &\ll r \leq R \end{aligned}$$

(c) The inertia free flow is governed by

$$\frac{\partial^2 u}{\partial z^2} = \frac{1}{\mu} \frac{dp}{dr}$$

subject to the boundary conditions

$$u = 0 \text{ at } z = 0$$

$$u = 0 \text{ at } z = h$$

The velocity is then given by

$$u = \frac{1}{2\mu} \frac{dp}{dr} (z^2 - zh)$$

The volume flow rate is

$$\begin{aligned} Q &= \frac{2\pi r}{2\mu} \frac{dp}{dr} \int_0^h (z^2 - zh) dz \\ &= -\frac{\pi r h^3}{6\mu} \frac{dp}{dr} \end{aligned}$$

The pressure distribution is therefore governed by

$$\begin{aligned} \frac{dp}{dr} &= -\frac{6\mu Q}{\pi h^3} \frac{1}{r} \\ \Rightarrow p(r) - p_o &= -\frac{6\mu Q}{\pi h^3} \ln\left(\frac{2r}{d}\right) \end{aligned}$$

At $r = D/2$, the gage pressure is zero so that

$$Q = \frac{\pi p_o h^3}{6\mu \ln(D/d)}$$

The force is balance by the pressure distribution

$$\begin{aligned} F &= \int_{d/2}^{D/2} p(r) 2\pi r dr \\ &= 2\pi \int_{d/2}^{D/2} p_o \left[1 - \frac{\ln(2r/d)}{\ln(D/d)}\right] r dr \\ &= \frac{\pi D^2 p_o}{4} \left[\frac{1 - (d/D)^2}{2 \ln(D/d)} \right] \end{aligned}$$

Problem 6.7

Refer to Figure 3 for the schematic. The flow is steady.

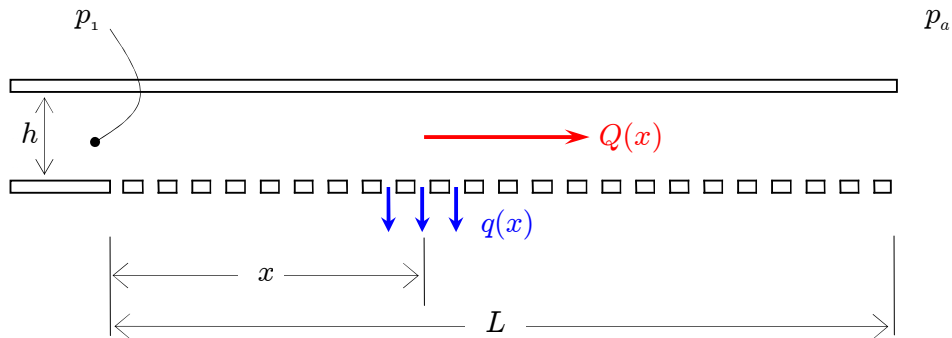


Figure 3: Schematic of Problem 6.7

(a) We apply the integral form of the conservation of mass for a control volume of height h and width dx ,

$$\begin{aligned} Q + \frac{dQ}{dx} dx + qw dx - Q &= 0 \\ \Rightarrow \frac{dQ}{dx} = -wq = -kw [p(x) - p_a] \end{aligned} \quad (1)$$

(b) The x -component of the momentum equation is

$$0 = -\frac{dp}{dx} + \mu \frac{\partial^2 u}{\partial y^2}$$

subject to the conditions $u = 0$ at $y = 0$ and $y = h$. The solution is

$$u = \frac{1}{2\mu} \frac{dp}{dx} (y^2 - hy)$$

leading to

$$Q = w \int_0^h u dy = -\frac{wh^3}{12\mu} \frac{dp}{dx}$$

Differentiating in x ,

$$\frac{dQ}{dx} = -\frac{wh^3}{12\mu} \frac{d^2p}{dx^2} \quad (2)$$

$$\Rightarrow \frac{d^2p}{dx^2} = \frac{12\mu k}{h^2} [p(x) - p_a] \quad (3)$$

subject to the conditions

$$\begin{aligned} p &= p_1 \text{ at } x = 0 \\ p &= p_a \text{ at } x = L \end{aligned}$$

(c) In this case we have a conventional Poiseuille flow. If q is very small, then k is very small. From equation (3)

$$\begin{aligned}\frac{d^2p}{dx^2} &\simeq 0 \\ \Rightarrow \frac{dp}{dx} &= \frac{p_a - p_1}{L}\end{aligned}$$

Therefore the location at which the gage pressure reaches half the inlet gage pressure is $x^* = L/2$.

(d) In this case $Q(x = L) \simeq 0$. A first order approximation in this case is to assume that Q varies linearly from $Q = Q_0$ at $x = 0$ to $Q = 0$ at $x = L$,

$$\begin{aligned}\frac{dQ}{dx} &\simeq -\frac{Q_0}{L} \\ \Rightarrow Q &\simeq Q_0 \left(1 - \frac{x}{L}\right)\end{aligned}$$

From equation (2),

$$\frac{wh^3}{12\mu} \frac{d^2p}{dx^2} = \frac{Q_0}{L}$$

Leading to the pressure distribution

$$p(x) = \frac{6\mu Q_0}{wh^3 L} x^2 + \left(\frac{p_a - p_1}{L} - \frac{6\mu Q_0}{wh^3}\right) x + p_1 \quad (4)$$

To get Q_0 , we integrate equation (1),

$$\begin{aligned}0 - Q_0 &= \int_0^L -kw [p(x) - p_a] dx \\ \Rightarrow Q_0 &= kw \int_0^L \left[\frac{6\mu Q_0}{wh^3 L} x^2 + \left(\frac{p_a - p_1}{L} - \frac{6\mu Q_0}{wh^3}\right) x + p_1 - p_a \right] dx \\ \Rightarrow Q_0 &= \frac{wh^3(p_1 - p_a)}{2\mu L + 2h^3/kL} \simeq \frac{wh^3(p_1 - p_a)}{2\mu L}\end{aligned}$$

Note $kL \gg h^3/\mu L$ in this case. Substituting Q_0 in equation (4), we get

$$\frac{p(x) - p_a}{p_1 - p_a} = 3\frac{x^2}{L^2} - 4\frac{x}{L} + 1$$

Now we find x^* such that $(p(x^*) - p_a)/(p_1 - p_a) = \frac{1}{2}$, resulting in $x^* = 0.14L$.

(e) The differential equation

$$\frac{d^2p^*}{dx^2} = \alpha p^*(x)$$

where $p^*(x) = \frac{p(x) - p_a}{p_1 - p_a}$ and $\alpha = \frac{12\mu k}{h^2}$ have the general solution

$$p^*(x) = C_1 e^{x\sqrt{\alpha}} + C_2 e^{-x\sqrt{\alpha}}$$

subject to the boundary conditions $p^* = 1$ at $x = 0$ and $p^* = 0$ at $x = L$, we get

$$\begin{aligned} C_1 + C_2 &= 1 \\ C_1 e^{L\sqrt{\alpha}} + C_2 e^{-L\sqrt{\alpha}} &= 0 \end{aligned}$$

leading to

$$\frac{p(x) - p_a}{p_1 - p_a} = \frac{e^{(L-x)\sqrt{\alpha}} - e^{-(L-x)\sqrt{\alpha}}}{e^{L\sqrt{\alpha}} - e^{-L\sqrt{\alpha}}}$$

- case 1: in the limit $k \rightarrow 0$, i.e. $\alpha = 0$,

$$\frac{p(x) - p_a}{p_1 - p_a} = \frac{L - x}{L}$$

at $x = L/2$, we get $\frac{p(x) - p_a}{p_1 - p_a} = 1/2$.

- case 2: in the limit $L\sqrt{\alpha} \gg 0$,

$$\frac{p(x) - p_a}{p_1 - p_a} = e^{-x\sqrt{\alpha}}$$

at $x = \frac{\ln(2)}{\sqrt{\alpha}}$, we get $\frac{p(x) - p_a}{p_1 - p_a} = 1/2$.

Problem 6.10

Refer to Figure 4 for the schematic.

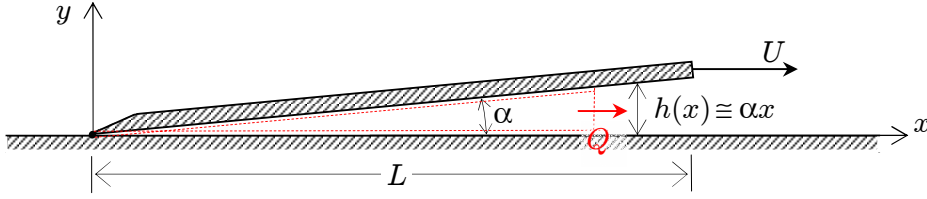


Figure 4: Schematic of Problem 6.10

(a) the ratio of the inertia to viscous forces is

$$\frac{\rho u \frac{\partial u}{\partial x}}{\mu \frac{\partial^2 u}{\partial y^2}} \sim \frac{\rho \frac{U^2}{x}}{\mu \frac{U}{\alpha^2 x^2}} = \frac{\rho U x}{\mu} \alpha^2 = \text{Re}_x \alpha^2$$

Therefore the criteria for modeling the flow as inertia free is to have $\text{Re}_x \alpha^2 \ll 1$.

(b) Locally Couette flow. The governing equation is

$$0 = -\frac{dp}{dx} + \mu \frac{\partial^2 u}{\partial y^2}$$

subject to the boundary conditions

$$\begin{aligned} u &= 0 \text{ at } y = 0 \\ u &= U \text{ at } y = h \end{aligned}$$

The velocity is then given by

$$u = -\frac{1}{2\mu} \frac{dp}{dx} (y^2 - yh) + U \frac{y}{h}$$

The volume flow rate is given by

$$\begin{aligned} Q &= \int_0^h u dy = \frac{h^3}{12\mu} \frac{dp}{dx} + \frac{Uh}{2} \\ &= \frac{\alpha^3 x^3}{12\mu} \frac{dp}{dx} + \frac{U\alpha x}{2} \end{aligned}$$

By applying the integral form of the conservation of mass for the control volume shown in Figure 4, we get¹

$$Q = 0$$

Then

$$\begin{aligned} \frac{dp}{dx} &= -\frac{6\mu U}{\alpha^2} \frac{1}{x^2} \\ \Rightarrow p - p_L &= \frac{6\mu U}{\alpha^2} \frac{L-x}{xL} \end{aligned}$$

¹It may be easier to get the result in a reference frame moving with the blade.

Problem 6.16

Refer to Figure 5 for the schematic.

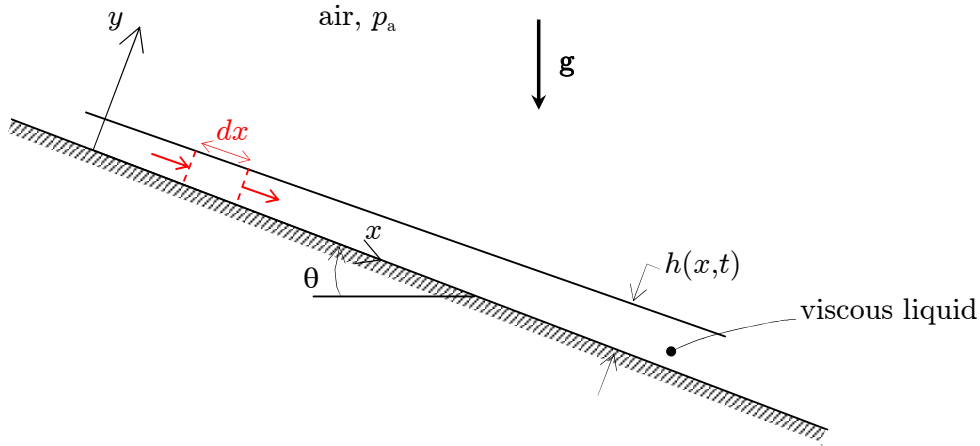


Figure 5: Schematic of Problem 6.16

(a) We apply conservation of mass for a control volume shown in the figure,

$$\begin{aligned}
 & \frac{\partial}{\partial t} \int_{CV} \rho dV + \int_{CS} \rho \mathbf{u} \cdot \hat{\mathbf{n}} dS = 0 \\
 \Rightarrow & \frac{\partial}{\partial t} (\rho h dx) + \rho \frac{dQ}{dx} dx = 0 \\
 \Rightarrow & \frac{\partial h}{\partial t} + \frac{dQ}{dx} = 0
 \end{aligned} \tag{5}$$

where Q is the volume flowrate. The differential form of the momentum conservation in the x -direction is

$$0 = \mu \frac{\partial^2 u}{\partial y^2} + \rho g \sin \theta$$

where the pressure gradient is zero and the inertia term is neglected. The boundary conditions are

$$\begin{aligned}
 u &= 0 \text{ at } y = 0 \\
 \tau &= \mu \frac{\partial u}{\partial y} = 0 \text{ at } y = h
 \end{aligned}$$

The velocity is then given by

$$u = \frac{\rho g \sin \theta}{\mu} \left(hy - \frac{y^2}{2} \right)$$

The volume flow rate is

$$\begin{aligned}
 Q &= \int_0^h u dy = \frac{\rho g \sin \theta}{3\mu} h^3 \\
 \Rightarrow \frac{dQ}{dx} &= \frac{\rho g \sin \theta}{\mu} h^2 \frac{dh}{dx}
 \end{aligned}$$

Combining with equation (5), we get

$$\frac{\partial h}{\partial t} + \frac{\rho g \sin \theta}{\mu} h^2 \frac{dh}{dx} = 0$$

(b)