



American University of Beirut
Faculty of Engineering & Architecture
Civil Engineering Department

EXAM [1] – SPRING 2014
(Tuesday, 18th March 2014)
CIVE410 – STRUCTURES II
CLOSED BOOK, 75 MINUTES

Name: SOLUTION AUB-ID#: ~

NOTES

- 3 PROBLEMS – 10 PAGES (INCLUDING THIS PAGE).
- READ PROBLEM STATEMENTS CAREFULLY.
- ASSUME ANY MISSING DATA YOU MAY REQUIRE. WRITE YOUR COMMENTS BELOW.
- ALL YOUR ANSWERS SHOULD BE PROVIDED ON THE QUESTION SHEETS.
- WELL ORGANIZED AND SYSTEMATIC SOLUTION WILL BE CREDITED. NEATNESS COUNTS.
- **TRY NOT TO USE THE BACK OF THE SHEETS FOR ANSWERS UNLESS YOU RUN OUT OF SPACE.**
- NOTE THE PERCENTAGE OF POINTS ASSIGNED FOR EACH PROBLEM.
- CHECK BOXES ARE FOR YOU TO CONFIRM YOU HAVE SOLVED A QUESTION



YOUR COMMENT(S)

DO NOT WRITE IN THE SPACE BELOW

MY COMMENT(S)

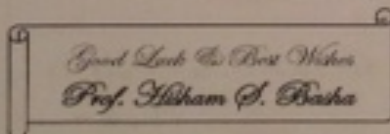
YOUR GRADE

Problem [1]: ___ /20

Problem [2]: ___ /30

Problem [3]: ___ /50

Other: ___



Problem [1]: (20 points)

Discuss Stability and Determinacy for the structures shown in the accompanying Figures.

Calculations and/or Diagrams:

[A] All reactions are concurrent at O \Rightarrow Geometrically Unstable.
 \therefore Structure is Unstable.

[B] $i = (3m+r) - (3j+h)$.

Composite system.

$$\left. \begin{array}{l} m = 15 \\ r = 4 \\ j = 8 \\ r' = 20 \end{array} \right\} \Rightarrow i = (45+4) - (24+20) = 49 - 44 = 5$$

OR $i = (3m+r) - (3j+h) + (m'+r') - 2j'$

$$\begin{array}{l} m = 3 ; m' = 12 \\ j = 4 ; j' = 4 \\ r = 4 ; r' = 0 \\ h = 0 \end{array}$$

$$\Rightarrow i = (9+4) - (12+0) + (12+0) - 8 = 13 - 12 + 4 = 5$$

System is stable & statically indeterminate of the 5th degree.

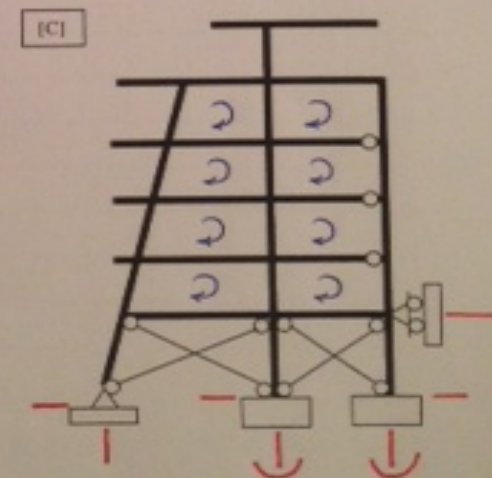
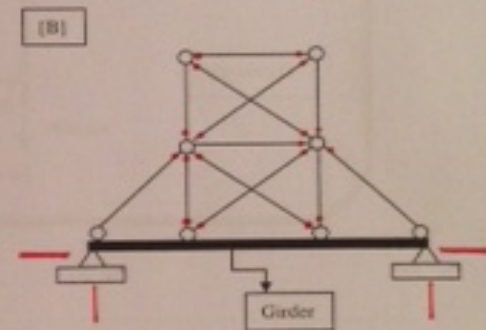
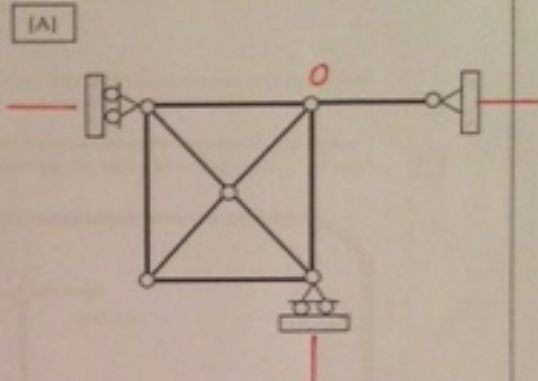
[C] $m = 36 ; r = 9 ; j = 25 ; h = 11$.

$$i = (3m+r) - (3j+h) = (108+9) - (75+11) = 117 - 86 = 31$$

OR

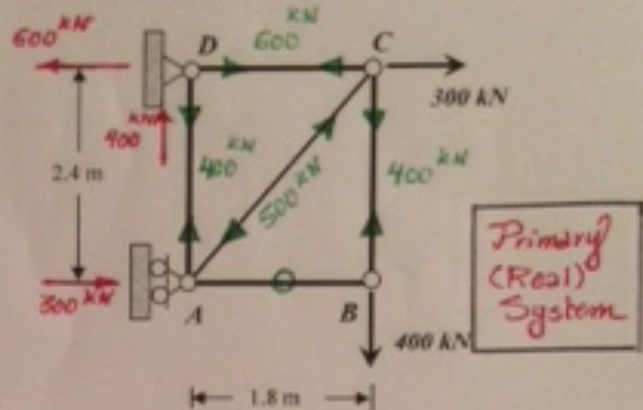
$$i = i_{ext} + i_{int} = 6 + (3 \times 8 + 4 - 3) = 6 + 25 = 31$$

System is stable & statically indet. to the 31st degree.



Reactions:-

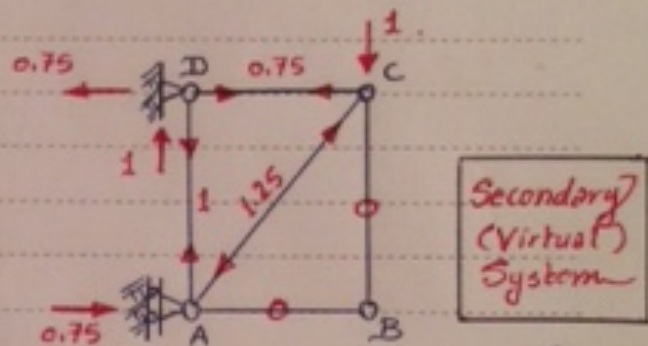
- $\sum M_D = 0 \Rightarrow X_A = 300 \text{ kN} \rightarrow$
- $\sum X = 0 \Rightarrow X_D = 600 \text{ kN} \leftarrow$
- $\sum Y = 0 \Rightarrow Y_D = 400 \text{ kN} \uparrow$



Calculations and Diagrams (cont'd):

P.V.W

$$\sum W_{ext} = \sum W_{int}$$



$$1 \cdot \Delta = \sum_{i=1}^n \left(\frac{N_i N_i L_i}{EA} \right)_i + \sum_{i=1}^n (N_i \cdot \alpha \cdot \Delta T \cdot L)_i + \sum_{i=1}^n (N_i \cdot \Delta L_{Fab})_i$$

$$1 \cdot \Delta_{C_{Vert.}} = \frac{(0.75)(600)(1.8)}{200 \times 10^6 \times 1200 \times 10^{-6}} + \frac{(1)(400)(2.4)}{200 \times 10^6 \times 1200 \times 10^{-6}} + \frac{(1.25)(500)(3)}{200(10^6) \times 300 \times 10^{-6}} +$$

$$(N_i \alpha \Delta T L)_{AD} = (1)(1.08)(10^{-3})(+60)(2.4)$$

$$\Rightarrow \Delta_{C_{Vert.}} = 0.003375 + 0.004 + 0.010417 + 0.0015552$$

$$= + 0.019347 \text{ m}$$

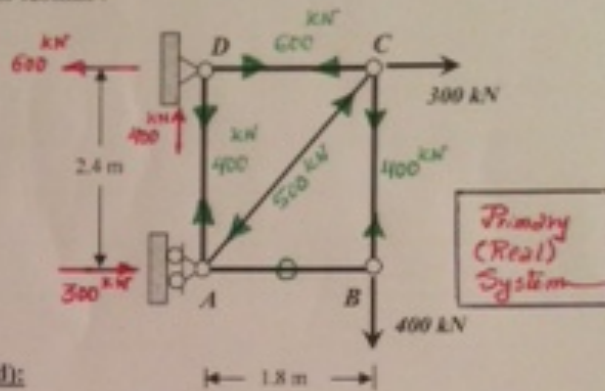
$$\Rightarrow \Delta_{C_{Vert.}} = 19.35 \text{ mm} (\downarrow)$$

Reactions :-

$$\sum M_D = 0 \Rightarrow X_B = 300 \text{ kN} \rightarrow$$

$$\sum X = 0 \Rightarrow X_D = 600 \text{ kN} \leftarrow$$

$$\sum Y = 0 \Rightarrow Y_D = 400 \text{ kN} \uparrow$$



Calculations and Diagrams (cont'd):

P.V.W.

$$\sum W_{ext} = \sum W_{int}$$

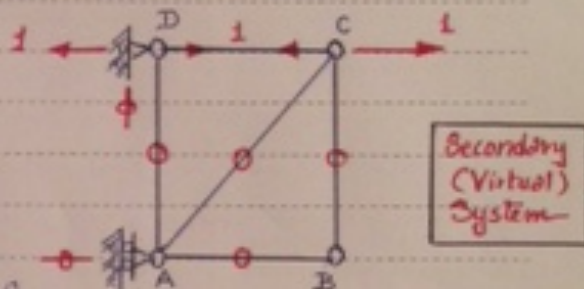
$$\Rightarrow 1 \cdot \Delta = \sum_{i=1}^n \frac{(N_i N_i L)_i}{EA}$$

$$\sum_{i=1}^n (N_i \alpha_i \Delta T_i L)_i + \sum_{i=1}^n (N_i \cdot S L_{i,cb})_i$$

$$\Rightarrow 1 \cdot \Delta_{C, Horiz.} = \frac{(600)(1) \cdot 1.8^m}{(EA)_{DC}} + 0 + (1)(+0.005^m)$$

$$\Rightarrow \Delta_{C, Horiz.} = \frac{(600)(1.8)}{200 \times 10^6 \times 1200 \times 10^{-6}} + 0.005^m = +0.0095^m$$

$$\Rightarrow \Delta_{C, Horiz.} = 9.5 \text{ mm} \rightarrow$$



Problem [3]: (50 points)

The frame $ABCDE$ shown in the accompanying figure (Figure 3) has a hinged support at A and roller support at B , as shown. Knowing that the horizontal beam CDE has a moment of inertia $(2I)$ whereas AC and BD have moments of inertia of (I) . Neglect axial and shear deformation.

Solve in terms of (EI) the following:

[A] Using the Energy Method (Virtual Work Concept), determine:

- The vertical displacement δ_E
- The slope θ_A at A .

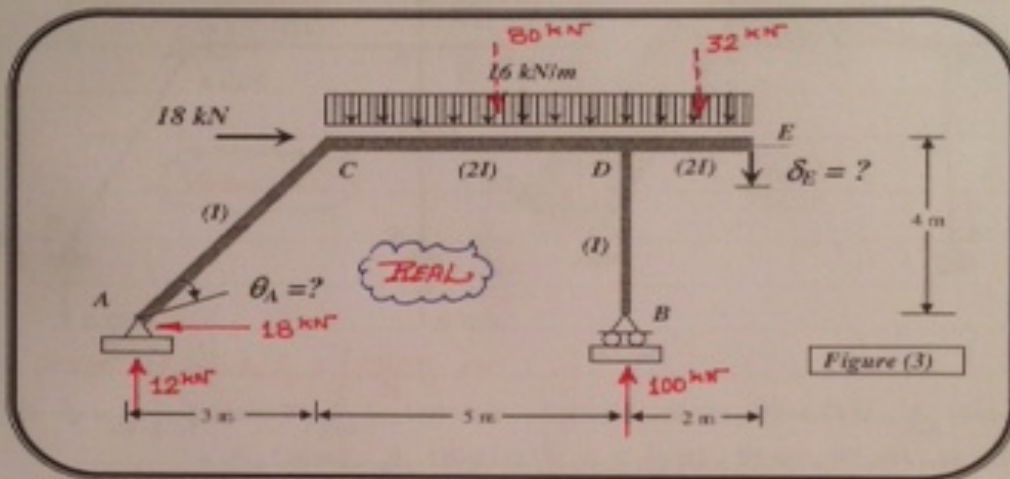
(20 points)



(15 points)

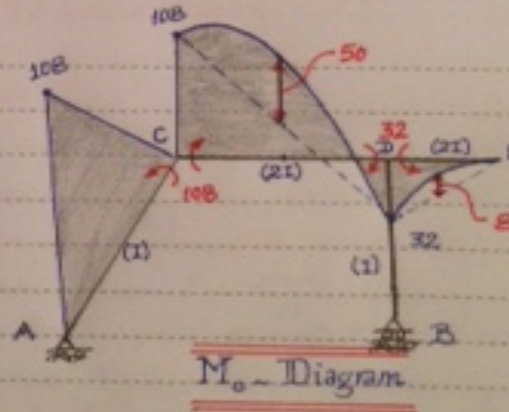
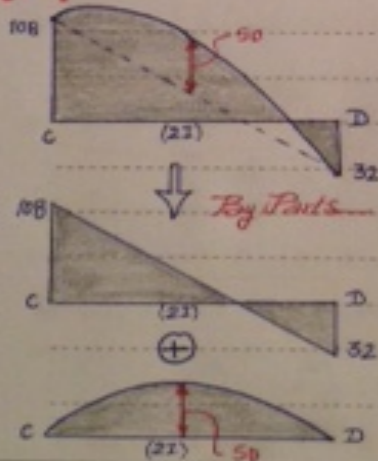


[B] If an external moment M_A is applied to restrain support A from rotation, compute by using the Energy Method (Virtual Work Concept), the value and direction of the restraining moment. (15 points)

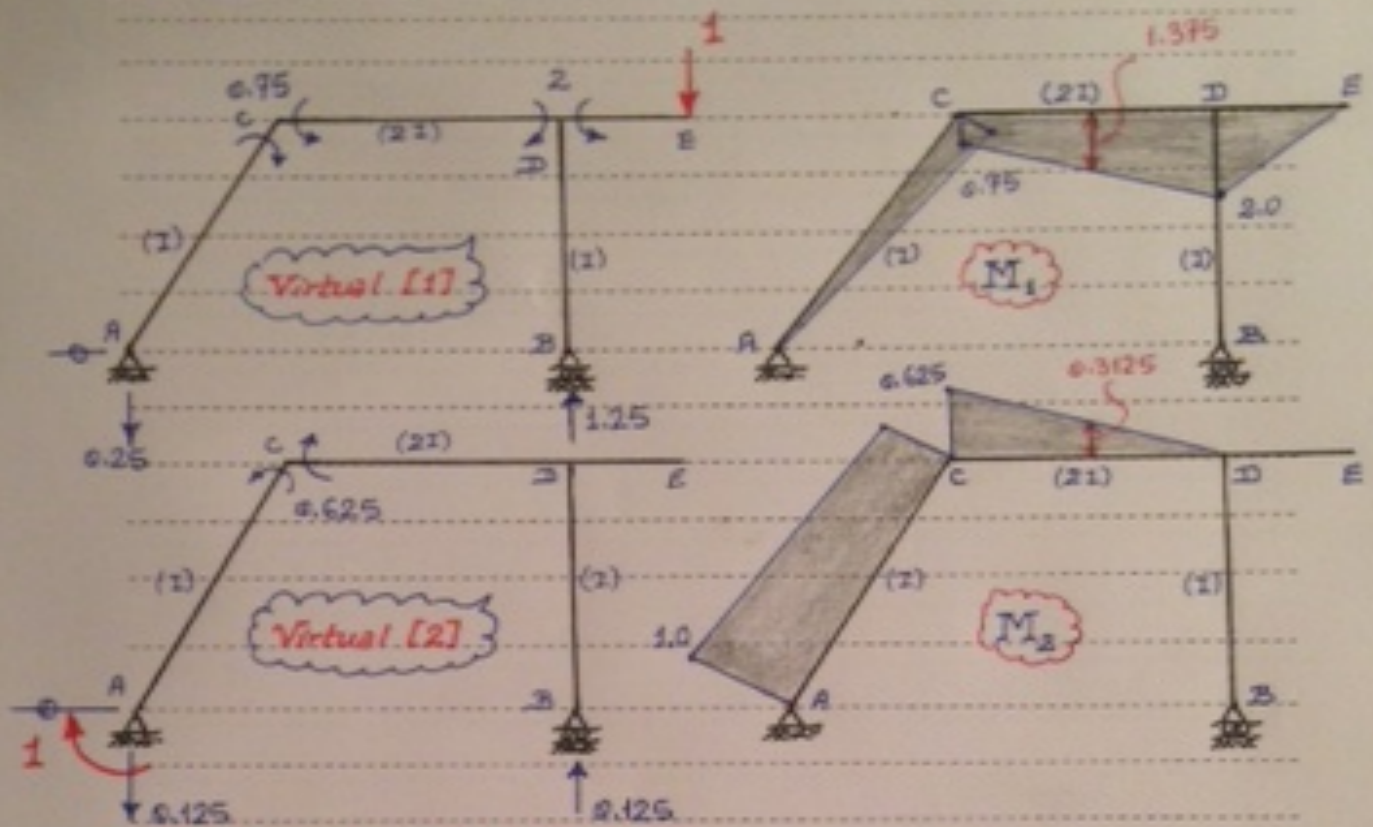


Calculations and Diagrams:

[A]



Calculations and Diagrams (cont'd):



\otimes P.V.W [1] $\Rightarrow 1 \cdot \delta_E = \int \frac{M_0 M_1}{EI} dx$
 $\Rightarrow \delta_E = \frac{1}{EI} \left\{ \frac{5}{3} (108)(0.35) + \frac{5}{2 \times 6} [-2(108)(0.35) + 2(32)(2) - 108(2) + 52(0.75)] - \frac{2}{2 \times 3} (5 \times 50)(1.375) \right.$
 $\left. + \frac{2}{2 \times 3} (32)(2) - \frac{2}{3 \times 2} (8 \times 2)(1) \right\} = \frac{1}{EI} \{-135 - 94.167 - 114.583 + 21.333 - 5.333\}$
 $\Rightarrow \delta_E = -\frac{327.75}{EI}$ (ve indicates opp. to assumed dummy load)

\otimes P.V.W [2] $\Rightarrow 1 \cdot \theta_A = \int \frac{M_0 M_2}{EI} dx$
 $\Rightarrow \theta_A = \frac{1}{EI} \left\{ \frac{5}{6} [0 + 2(108)(0.625) + 1(108) + 0] + \frac{5}{2 \times 6} [2(108)(0.625) + 0 + 0 - 32(0.625)] \right.$
 $\left. + \frac{2}{3 \times 2} (50 \times 5)(0.3125) \right\} = \frac{1}{EI} \{202.5 + 47.917 + 26.0417\}$
 $\Rightarrow \theta_A = \frac{276.46}{EI}$ (CW) (ve indicates in the direction of the dummy moment)

[B] From part [A] $\Rightarrow \theta_A = \frac{276.46}{EI}$ (CW)

It is required to determine the value of applied moment M_A that will restrain support A; i.e. M_A will cause $\frac{276.46}{EI}$ (CCW) for compatibility.

$\Rightarrow \int f_{20} + M_A \cdot f_{22} = f_{20} = 0 \Rightarrow M_A = -\frac{f_{20}}{f_{22}}$; knowing that $f_{20} = \int \frac{M_0 M_0}{EI} dx = \frac{276.46}{EI}$
 and $f_{22} = \int \frac{M_0 M_0}{EI} dx = \frac{5}{6EI} [2(0)(0) + 2(0.625)^2 + 2(0.625)(1) + 0.625(1)] + \frac{5}{3 \times 2EI} (0.625 \times 0.625)$
 $= \frac{1}{EI} (3.36 + 0.325) = \frac{3.686}{EI}$ (CW) $\Rightarrow M_A = -\frac{276.46}{3.686} = -75$ (CCW)

\therefore Restraining Moment $M_A = 95 \text{ kN-m}$ (CCW)

