



$L_i = L$   
 $A_i = A$   
 $E$   
 $\therefore K_i = \frac{AE}{L} = \text{constant}$

1. The stiffness matrix of any truss member  $i$  is of the following form:

$$= \begin{bmatrix} K_i \cos^2 \alpha_i & K_i \cos \alpha_i \sin \alpha_i & -K_i \cos \alpha_i & -K_i \cos \alpha_i \sin \alpha_i \\ K_i \sin \alpha_i \cos \alpha_i & K_i \sin^2 \alpha_i & -K_i \sin \alpha_i & -K_i \sin \alpha_i \cos \alpha_i \\ -K_i \cos \alpha_i & -K_i \cos \alpha_i \sin \alpha_i & K_i \cos^2 \alpha_i & K_i \cos \alpha_i \sin \alpha_i \\ -K_i \sin \alpha_i & -K_i \sin \alpha_i \cos \alpha_i & K_i \sin \alpha_i & K_i \sin^2 \alpha_i \end{bmatrix}$$

$$= \begin{bmatrix} K_i & -K_i \\ -K_i & K_i \end{bmatrix} \quad \text{where} \quad K_i = \begin{bmatrix} K_i \cos^2 \alpha_i & K_i \cos \alpha_i \sin \alpha_i \\ K_i \sin \alpha_i \cos \alpha_i & K_i \sin^2 \alpha_i \end{bmatrix}$$

Member	$\alpha_i$	$\cos \alpha_i$	$\sin \alpha_i$	$\cos^2 \alpha_i$	$\sin^2 \alpha_i$	$\cos \alpha_i \sin \alpha_i$
① & ⑤	$60^\circ$	$1/2$	$\sqrt{3}/2$	$1/4$	$3/4$	$\sqrt{3}/4$
②, ④, & ⑥	$0$	$1$	$0$	$1$	$0$	$0$
③ & ⑦	$120^\circ$	$-1/2$	$\sqrt{3}/2$	$1/4$	$3/4$	$-\sqrt{3}/4$

Members ① & ⑤:  $K_i = \begin{bmatrix} \frac{1}{4}K & \frac{\sqrt{3}}{4}K \\ \frac{\sqrt{3}}{4}K & \frac{3}{4}K \end{bmatrix}$

Members ②, ④, and ⑥:  $K_i = \begin{bmatrix} K & 0 \\ 0 & 0 \end{bmatrix}$

Members ③ & ⑦:  $K_i = \begin{bmatrix} \frac{1}{4}K & -\frac{\sqrt{3}}{4}K \\ -\frac{\sqrt{3}}{4}K & \frac{3}{4}K \end{bmatrix}$

∴

Members ① &amp; ⑤ :

$$\begin{bmatrix} \frac{-1}{4}k & \frac{\sqrt{3}}{4}k & -\frac{1}{4}k & -\frac{\sqrt{3}}{4}k \\ \frac{\sqrt{3}}{4}k & \frac{3}{4}k & -\frac{\sqrt{3}}{4}k & -\frac{3}{4}k \\ -\frac{1}{4}k & -\frac{\sqrt{3}}{4}k & \frac{1}{4}k & \frac{\sqrt{3}}{4}k \\ -\frac{\sqrt{3}}{4}k & -\frac{3}{4}k & \frac{\sqrt{3}}{4}k & \frac{3}{4}k \end{bmatrix}$$

Members ②, ④, &amp; ⑥ :

$$\begin{bmatrix} k & 0 & -k & 0 \\ 0 & 0 & 0 & 0 \\ -k & 0 & k & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Members ③ &amp; ⑦ :

$$\begin{bmatrix} \frac{1}{4}k & -\frac{\sqrt{3}}{4}k & -\frac{1}{4}k & +\frac{\sqrt{3}}{4}k \\ -\frac{\sqrt{3}}{4}k & \frac{3}{4}k & \frac{\sqrt{3}}{4}k & -\frac{3}{4}k \\ -\frac{1}{4}k & +\frac{\sqrt{3}}{4}k & \frac{1}{4}k & -\frac{\sqrt{3}}{4}k \\ \frac{\sqrt{3}}{4}k & -\frac{3}{4}k & -\frac{\sqrt{3}}{4}k & \frac{3}{4}k \end{bmatrix}$$

2.

	1	2	3	4	5		
1	$K_1+K_2$	$-K_1$	$-K_2$			$U_1$	$P_1$
2	$-K_1$	$K_1+K_3+K_4$	$-K_3$	$-K_4$		$U_2$	$P_2$
3	$-K_2$	$-K_3$	$K_2+K_3+K_5+K_6$	$-K_5$	$-K_6$	$U_3$	$P_3$
4		$-K_4$	$-K_5$	$K_4+K_5+K_7$	$-K_7$	$U_4$	$P_4$
5			$-K_5$	$-K_7$	$K_6+K_7$	$U_5$	$P_5$

or

	1	2	3	4	5						
1	$\frac{5k}{4}$	$\frac{\sqrt{3}k}{4}$	$-\frac{1}{4}k$	$-\frac{\sqrt{3}k}{4}$	$-k$	0	0	0	0	$U_1$	$X_1$
	$\frac{\sqrt{3}k}{4}$	$\frac{3k}{4}$	$-\frac{\sqrt{3}k}{4}$	$-\frac{3k}{4}$	0	0	0	0	0	$V_1$	$Y_1$
2	$-\frac{1}{4}k$	$-\frac{\sqrt{3}k}{4}$	$\frac{3k}{2}$	0	$-\frac{1}{4}k$	$\frac{\sqrt{3}k}{4}$	$-k$	0	0	0	0
	$-\frac{\sqrt{3}k}{4}$	$-\frac{3k}{4}$	0	$\frac{3k}{2}$	$\frac{\sqrt{3}k}{4}$	$-\frac{3k}{4}$	0	0	0	0	0
3	$-k$	0	$-\frac{1}{4}k$	$\frac{\sqrt{3}k}{4}$	$\frac{5k}{2}$	0	$-\frac{1}{4}k$	$-\frac{\sqrt{3}k}{4}$	$-k$	0	0
	0	0	$\frac{\sqrt{3}k}{4}$	$-\frac{3k}{4}$	0	$\frac{3k}{2}$	$-\frac{\sqrt{3}k}{4}$	$-\frac{3k}{4}$	0	0	$-P$
4	0	0	$-k$	0	$-\frac{1}{4}k$	$-\frac{\sqrt{3}k}{4}$	$\frac{3k}{2}$	0	$-\frac{1}{4}k$	$\frac{\sqrt{3}k}{4}$	0
	0	0	0	0	$-\frac{\sqrt{3}k}{4}$	$-\frac{3k}{4}$	0	$\frac{3k}{2}$	$\frac{\sqrt{3}k}{4}$	$-\frac{3k}{4}$	0
5	0	0	0	0	$-k$	0	$-\frac{1}{4}k$	$\frac{\sqrt{3}k}{4}$	$\frac{5k}{2}$	$-\frac{\sqrt{3}k}{4}$	0
	0	0	0	0	0	0	$\frac{\sqrt{3}k}{4}$	$-\frac{3k}{4}$	$\frac{\sqrt{3}k}{4}$	$\frac{3k}{4}$	0

Total stiffness matrix of truss as a free body (without support conditions)

3.

(a) Partitioning Technique

First step is interchanging the columns :

$-\frac{1}{4}k$	$\frac{\sqrt{3}k}{4}$	$-k$	0	0	0	$\frac{5k}{4}$	$\frac{\sqrt{3}k}{4}$	0	0
$-\frac{\sqrt{3}k}{4}$	$-\frac{3k}{4}$	0	0	0	0	$\frac{\sqrt{3}k}{4}$	$\frac{3k}{4}$	0	0
$\frac{3k}{2}$	0	$-\frac{1}{4}k$	$\frac{\sqrt{3}k}{4}$	$-k$	0	$-\frac{1}{4}k$	$-\frac{\sqrt{3}k}{4}$	0	0
0	$\frac{3k}{2}$	$\frac{\sqrt{3}k}{4}$	$-\frac{3k}{4}$	0	0	$-\frac{\sqrt{3}k}{4}$	$-\frac{3k}{4}$	0	0
$-\frac{1}{4}k$	$\frac{\sqrt{3}k}{4}$	$\frac{5k}{2}$	0	$-\frac{1}{4}k$	$-\frac{\sqrt{3}k}{4}$	$-k$	0	$-k$	0
$\frac{\sqrt{3}k}{4}$	$-\frac{3k}{4}$	0	$\frac{3k}{2}$	$-\frac{\sqrt{3}k}{4}$	$-\frac{3k}{4}$	0	0	0	0
$-k$	0	$-\frac{1}{4}k$	$-\frac{\sqrt{3}k}{4}$	$\frac{3k}{2}$	0	0	0	$-\frac{1}{4}k$	$\frac{\sqrt{3}k}{4}$
0	0	$-\frac{\sqrt{3}k}{4}$	$-\frac{3k}{4}$	0	$\frac{3k}{2}$	0	0	$\frac{\sqrt{3}k}{4}$	$-\frac{3k}{4}$
0	0	$-k$	0	$-\frac{1}{4}k$	$\frac{\sqrt{3}k}{4}$	0	0	$\frac{5k}{4}$	$-\frac{\sqrt{3}k}{4}$
0	0	0	0	$\frac{\sqrt{3}k}{4}$	$-\frac{3k}{4}$	0	0	$-\frac{\sqrt{3}k}{4}$	$\frac{3k}{4}$

2<sup>nd</sup> step is interchanging the rows :

$\frac{3k}{2}$	0	$-\frac{1}{4}k$	$\frac{\sqrt{3}k}{4}$	$-k$	0	$-\frac{1}{4}k$	$-\frac{\sqrt{3}k}{4}$	0	0	$u_2$	0
0	$\frac{3k}{2}$	$\frac{\sqrt{3}k}{4}$	$-\frac{3k}{4}$	0	0	$-\frac{\sqrt{3}k}{4}$	$-\frac{3k}{4}$	0	0	$v_2$	0
$-\frac{1}{4}k$	$\frac{\sqrt{3}k}{4}$	$\frac{5k}{2}$	0	$-\frac{1}{4}k$	$-\frac{\sqrt{3}k}{4}$	$-k$	0	$-k$	0	$u_3$	0
$\frac{\sqrt{3}k}{4}$	$-\frac{3k}{4}$	0	$\frac{3k}{2}$	$-\frac{\sqrt{3}k}{4}$	$-\frac{3k}{4}$	0	0	0	0	$v_3$	-P
$-k$	0	$-\frac{1}{4}k$	$-\frac{\sqrt{3}k}{4}$	$\frac{3k}{2}$	0	0	0	$-\frac{1}{4}k$	$\frac{\sqrt{3}k}{4}$	$u_4$	0
0	0	$-\frac{\sqrt{3}k}{4}$	$-\frac{3k}{4}$	0	$\frac{3k}{2}$	0	0	$\frac{\sqrt{3}k}{4}$	$-\frac{3k}{4}$	$v_4$	0
$-\frac{1}{4}k$	$-\frac{\sqrt{3}k}{4}$	$-k$	0	0	0	$\frac{5k}{4}$	$\frac{\sqrt{3}k}{4}$	0	0	$u_1$	$X_1$
$\frac{\sqrt{3}k}{4}$	$-\frac{3k}{4}$	0	0	0	0	$\frac{\sqrt{3}k}{4}$	$\frac{3k}{4}$	0	0	$v_1$	$Y_1$
0	0	$-k$	0	$-\frac{1}{4}k$	$\frac{\sqrt{3}k}{4}$	0	0	$\frac{5k}{4}$	$-\frac{\sqrt{3}k}{4}$	$u_5$	$X_5$
0	0	0	0	$\frac{\sqrt{3}k}{4}$	$-\frac{3k}{4}$	0	0	$-\frac{\sqrt{3}k}{4}$	$\frac{3k}{4}$	$v_5$	$Y_5$

↑  
stiffness matrix of the free joints

## (b) MIT Method

The degrees of freedom  $u_1, v_1, u_3,$  and  $v_3$  are zero's.

∴ Referring back to the Stiffness matrix at the bottom of page 2:

- Make all terms of the 1<sup>st</sup>, 2<sup>nd</sup>, 9<sup>th</sup>, and 10<sup>th</sup> rows = 0
- Make all terms of the 1<sup>st</sup>, 2<sup>nd</sup>, 9<sup>th</sup>, and 10<sup>th</sup> columns = 0
- Make the terms (1,1), (2,2), (9,9), (10,10) = 1
- Make the 1<sup>st</sup>, 2<sup>nd</sup>, 9<sup>th</sup>, and 10<sup>th</sup> terms of the load vector = 0

1	0	0	0	0	0	0	0	0	0	$u_1$	0
0	1	0	0	0	0	0	0	0	0	$v_1$	0
0	0	$\frac{3k}{2}$	0	$-\frac{1k}{4}$	$\frac{\sqrt{3}k}{4}$	-k	0	0	0	$u_2$	0
0	0	0	$\frac{3k}{2}$	$\frac{\sqrt{3}k}{4}$	$-\frac{3k}{4}$	0	0	0	0	$v_2$	0
0	0	$-\frac{1k}{4}$	$\frac{\sqrt{3}k}{4}$	$\frac{5k}{2}$	0	$-\frac{1k}{4}$	$-\frac{\sqrt{3}k}{4}$	0	0	$u_3$	0
0	0	$\frac{\sqrt{3}k}{4}$	$-\frac{3k}{2}$	0	$\frac{3k}{2}$	$-\frac{\sqrt{3}k}{4}$	$-\frac{3k}{4}$	0	0	$v_3$	-P
0	0	-k	0	$-\frac{1k}{4}$	$-\frac{\sqrt{3}k}{4}$	$\frac{3k}{2}$	0	0	0	$u_4$	0
0	0	0	0	$-\frac{\sqrt{3}k}{4}$	$-\frac{3k}{4}$	0	$\frac{3k}{2}$	0	0	$v_4$	0
0	0	0	0	0	0	0	0	1	0	$u_5$	0
0	0	0	0	0	0	0	0	0	1	$v_5$	0

same as in method (a);  
this is the stiffness matrix  
for the free joints.

(c) Berkeley Method

In the stiffness matrix at the bottom of page  
② apply the following modifications:

- Add  $10^{10}$  to the terms (1,1), (2,2), (9,9), and (10,10)
- Make 0 the 1<sup>st</sup>, 2<sup>nd</sup>, 9<sup>th</sup>, and 10<sup>th</sup> terms of the load vector