

Problem # 1

Based on the spectrum of a PAM signal, the bandwidth of the signal is determined by that of the rectangular pulse whose duration is equal to T . Thus, the PAM signal bandwidth is equal to $\frac{1}{T}$ by the first zero crossing bandwidth definition. Hence, the smallest bandwidth is obtained when $T = T_s$. But, $\frac{1}{T_s} = 2 \times 5000 = 10,000$ samples/sec
 $\Rightarrow T = T_s = 10^{-4}$ sec = 0.1 μ s.

Problem # 2

The pulse duration of a PDM signal is given by:

$$PD = k e^{[m(nT_s) / \max(m(nT_s))]}$$

Since the pulse duration in a PDM signal is proportional to the value of the sample from the message signal, then $(PD)_{\max}$ is obtained when $m(nT_s) = \max(m(nT_s))$. Hence,

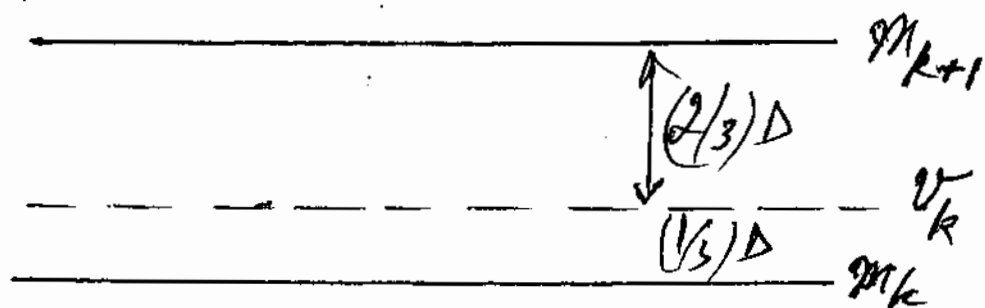
$$(PD)_{\max} = T_s = k e^{[\max m(nT_s) / \max m(nT_s)]} = k e$$
$$\Rightarrow k = T_s / e.$$

$$(PD)_{\min} = \frac{T_s}{e} e^{\frac{L \max m(nT_s) / \max m(nT_s)}{X(0)}} \\ = \frac{T_s}{e} e^{[-2/2]} = \frac{T_s}{e^2}$$

Here, we used $\min m(nT_s) = -2$ and $\max m(nT_s) = 2$ since the message has a dynamic range between -2 volts and 2 volts and since the sampling rate is much bigger than the Nyquist rate. This means that T_s is very small and sample values at -2 and 2 volts will be obtained.

(or very close values)

Problem # 3



Based on the above representation of v_k in cell (m_k, m_{k+1}) , the range of the quantization noise, represented by $Q = M - V$ is $[-\frac{1}{3}\Delta, \frac{2}{3}\Delta]$.

Now, since Q is uniformly distributed, then

$$f_Q(q) = \begin{cases} \frac{1}{\Delta}, & -\frac{1}{3}\Delta \leq q \leq \frac{2}{3}\Delta \\ 0, & \text{elsewhere.} \end{cases}$$

$$\begin{aligned} E(Q^2) &= \int_{-\frac{1}{3}\Delta}^{\frac{2}{3}\Delta} \frac{1}{\Delta} q^2 dq = \frac{1}{3\Delta} q^3 \Big|_{-\frac{1}{3}\Delta}^{\frac{2}{3}\Delta} \\ &= \frac{1}{3\Delta} \left[\left(\frac{2}{3}\right)^3 \Delta^3 + \left(\frac{1}{3}\right)^3 \Delta^3 \right] \\ &= \frac{\Delta^2}{3} \left[\frac{8+1}{27} \right] = \frac{\Delta^2}{9} \end{aligned}$$

Problem #4

Based on the result in problem #3; i.e., $E(Q^2) = \frac{\Delta^2}{9}$, and the fact that $E[Q^2] = \frac{\Delta^2}{12}$ when V_k is the midpoint of cell (m_k, m_{k+1}) , then it is better to place V_k at the midpoint of the cell because it gives a smaller average power of the quantization noise. The midpoint is also better than all other indicated positions of V_k in cell (m_k, m_{k+1}) . Since this can be checked easily by calculating $E(Q^2)$.

Problem # 5

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The compression of the analog signal reduces its dynamic range and this allows the use of a smaller number of quantization levels compared to the number of levels used for the uncompressed signal.

Problem # 6

$$\begin{aligned} \text{The bit rate in PCM} &= \frac{\log_2 L}{(T_s)_{\text{PCM}}} = \frac{\log_2 256}{(T_s)_{\text{PCM}}} \\ &= 8 \times 2 \times 5000 = 80,000 \text{ bits/sec} \end{aligned}$$

$$\text{The bit rate in DM} = \frac{1}{(T_s)_{\text{DM}}} = 80,000 \text{ bits/sec.}$$

$$\Rightarrow \text{Sampling rate in DM} = 80,000 \text{ samples/sec.}$$

Problem # 7

$$\begin{aligned} \text{Bit rate in PCM} &= \frac{\log_2 \left(\frac{16}{0.0625} \right)}{T_s} \\ &= \frac{\log_2 256}{T_s} = \frac{8}{T_s} \end{aligned}$$

$$\text{Bit rate in DPCM} = \frac{3}{4} \times \frac{8}{T_s} = \frac{\log_2 \left(\frac{DR}{0.0625} \right)}{T_s}$$

$$\text{Hence, } \log_2 \left(\frac{DR}{0.0625} \right) = 6$$

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$$\Rightarrow DR = 0.0625 \times 2^6 = 4 \text{ Volts.}$$

Problem # 8

$$(SNR)_{PCM} = \frac{\sigma_M^2}{\frac{(\Delta)_{PCM}^2}{12}} = \frac{12 \sigma_M^2}{\left(\frac{16}{256}\right)^2}$$

$$(SNR)_{DPCM} = \frac{\sigma_M^2}{\frac{(\Delta)_{DPCM}^2}{12}} = \frac{12 \sigma_M^2}{\left(\frac{8}{256}\right)^2}$$

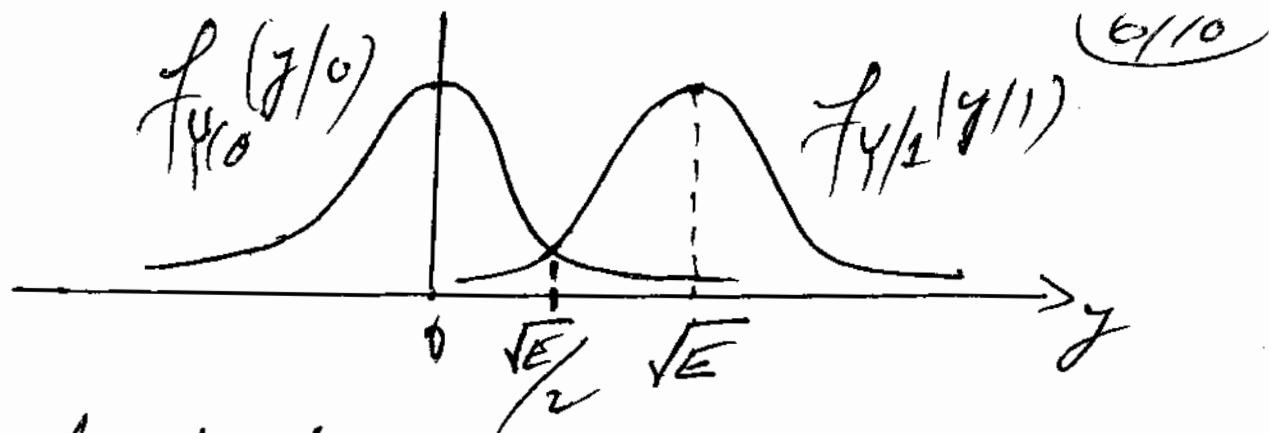
$$\Rightarrow (SNR)_{DPCM} = 4 (SNR)_{PCM}$$

Problem # 9

$$Y = \begin{cases} \sqrt{E} + W, & \text{if bit 1 is sent} \\ W, & \text{if bit 0 is sent} \end{cases}$$

$$f_{Y|1}(y|1) = \frac{1}{\sqrt{\pi N_0}} \exp\left\{-\frac{1}{2} \frac{(y - \sqrt{E})^2}{N_0/2}\right\}$$

$$f_{Y|0}(y|0) = \frac{1}{\sqrt{\pi N_0}} \exp\left\{-\frac{1}{2} \frac{y^2}{N_0/2}\right\}.$$



Under $p_0 = p_1 = 1/2$, the maximum probability of error criterion gives the maximum likelihood decision rule. Hence, $\lambda = \frac{\sqrt{E}}{2}$.

Problem #10

$$y(iT_b) = \sum_{k=1}^L A_k p[(i-k)T_b]$$

$$y(3T_b) = \underbrace{A_1 p[2T_b] + A_2 p(T_b)}_{\text{ISI term}} + \underbrace{A_3 p(0)}_{\text{Signal term}}$$

$A_3 = -A$ since third bit is 0

$A_2 = A$ since 2nd bit is 1

$A_1 = -A$ since first bit is 0.

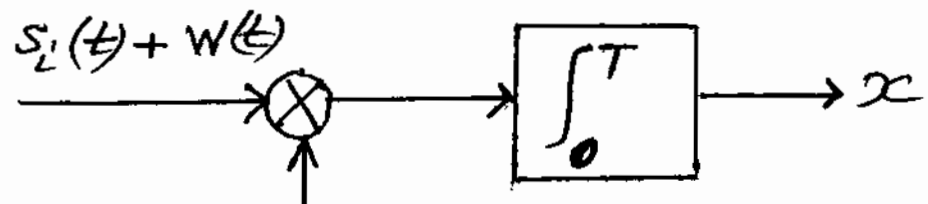
With $p(t) = e^{-|t|}$, for all t , then:

$$\begin{aligned} \text{ISI term} &= -A e^{-2T_b} + A e^{-T_b} \\ &= A [e^{-T_b} - e^{-2T_b}] \end{aligned}$$

Problem # 11

(7/10)

$s_i(t) = i \sqrt{\frac{2E}{T}} \cos(\omega_c t), \quad 0 \leq t \leq T,$
 where $i = -2, -1, 1, 2$.



$$\phi(t) = \sqrt{\frac{2E}{T}} \cos(\omega_c t)$$

$$X = i \int_0^T \frac{2\sqrt{E}}{T} \cos^2(\omega_c t) dt + \int_0^T W(t) \phi(t) dt$$

$$= i \frac{\sqrt{E}}{T} \left[\int_0^T dt + \int_0^T \cos(2\omega_c t) dt \right] + W_1$$

$$= i\sqrt{E} + W_1, \quad i = -2, -1, 1, 2.$$

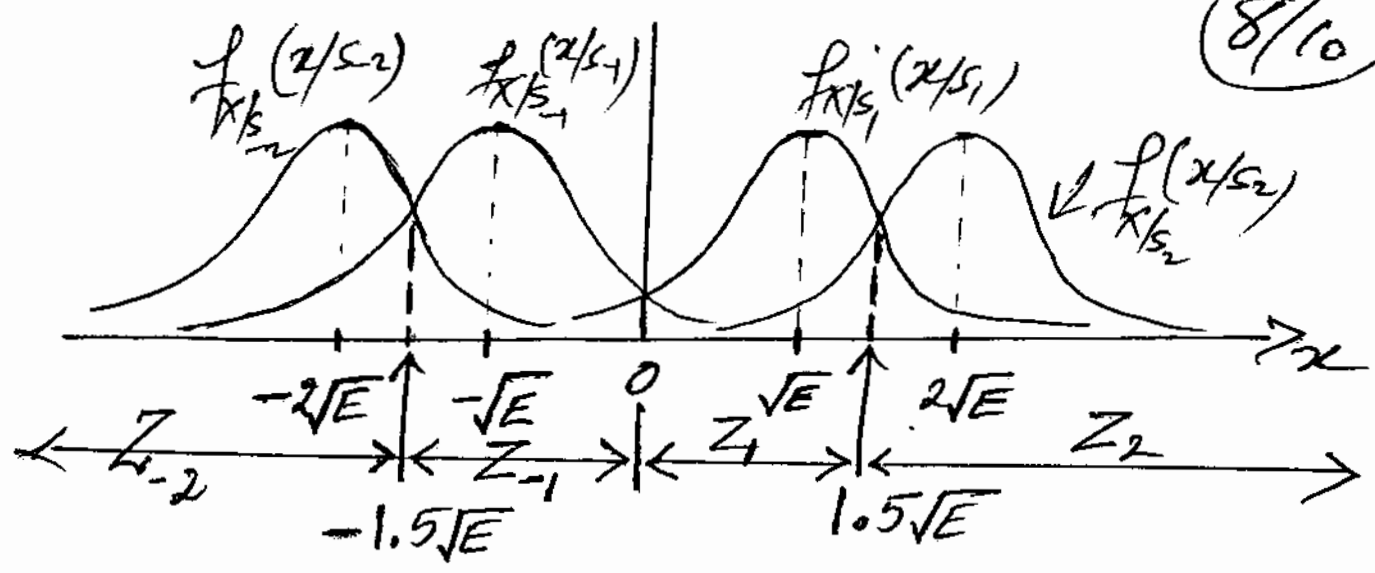
W_1 is a zero mean Gaussian random variable with variance equal to $N_0/2$. Hence, the probability density functions of the random variable X under the transmission of $s_i(t), i = -2, -1, 1, 2$ are:

$$f_{X/s_{-2}}(x/s_{-2}) = \frac{1}{\sqrt{\pi N_0}} \exp\left\{-\frac{1}{2} \frac{(x + 2\sqrt{E})^2}{N_0/2}\right\}$$

$$f_{X/s_{-1}}(x/s_{-1}) = \frac{1}{\sqrt{\pi N_0}} \exp\left\{-\frac{1}{2} \frac{(x + \sqrt{E})^2}{N_0/2}\right\}$$

$$f_{X/s_1}(x/s_1) = \frac{1}{\sqrt{\pi N_0}} \exp\left\{-\frac{1}{2} \frac{(x - \sqrt{E})^2}{N_0/2}\right\}$$

$$f_{X/s_2}(x/s_2) = \frac{1}{\sqrt{\pi N_0}} \exp\left\{-\frac{1}{2} \frac{(x - 2\sqrt{E})^2}{N_0/2}\right\}$$



The minimum probability of error criterion under equally probable transmitted signal gives the maximum likelihood decision rule.

Hence, the decision rule becomes:

- If $0 < x < 1.5\sqrt{E}$, decide $s_1(t)$.
- $-1.5\sqrt{E} < x < 0$, decide $s_1(t)$
- $1.5\sqrt{E} < x < \infty$, decide $s_2(t)$
- $-\infty < x < -1.5\sqrt{E}$, decide $s_2(t)$.

Of course, the above decision rule can also be obtained using the general structure of decision making device as obtained in class notes.

Problem #12

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$$s_1(t) = \sqrt{\frac{2E}{T}} \cos(\omega_c t), \quad 0 \leq t \leq T$$

$$s_2(t) = \sqrt{\frac{2E}{T}} \cos(\omega_c t - \frac{\pi}{2}), \quad 0 \leq t \leq T$$

$$s_3(t) = \sqrt{\frac{2E}{T}} \cos(\omega_c t + \frac{\pi}{2}), \quad 0 \leq t \leq T$$

$$s_4(t) = \sqrt{\frac{2E}{T}} \cos(\omega_c t + \pi), \quad 0 \leq t \leq T$$

$s_4(t)$ is linearly dependent on $s_1(t)$.

$s_3(t)$ is linearly dependent on $s_2(t)$.

Hence, according to the Gram-Schmidt procedure, $s_1(t)$ and $s_2(t)$ can be used to construct 2 orthonormal functions $\phi_1(t)$ and $\phi_2(t)$.

$$\phi_1(t) = \sqrt{\frac{2}{T}} \cos(\omega_c t), \quad 0 \leq t \leq T$$

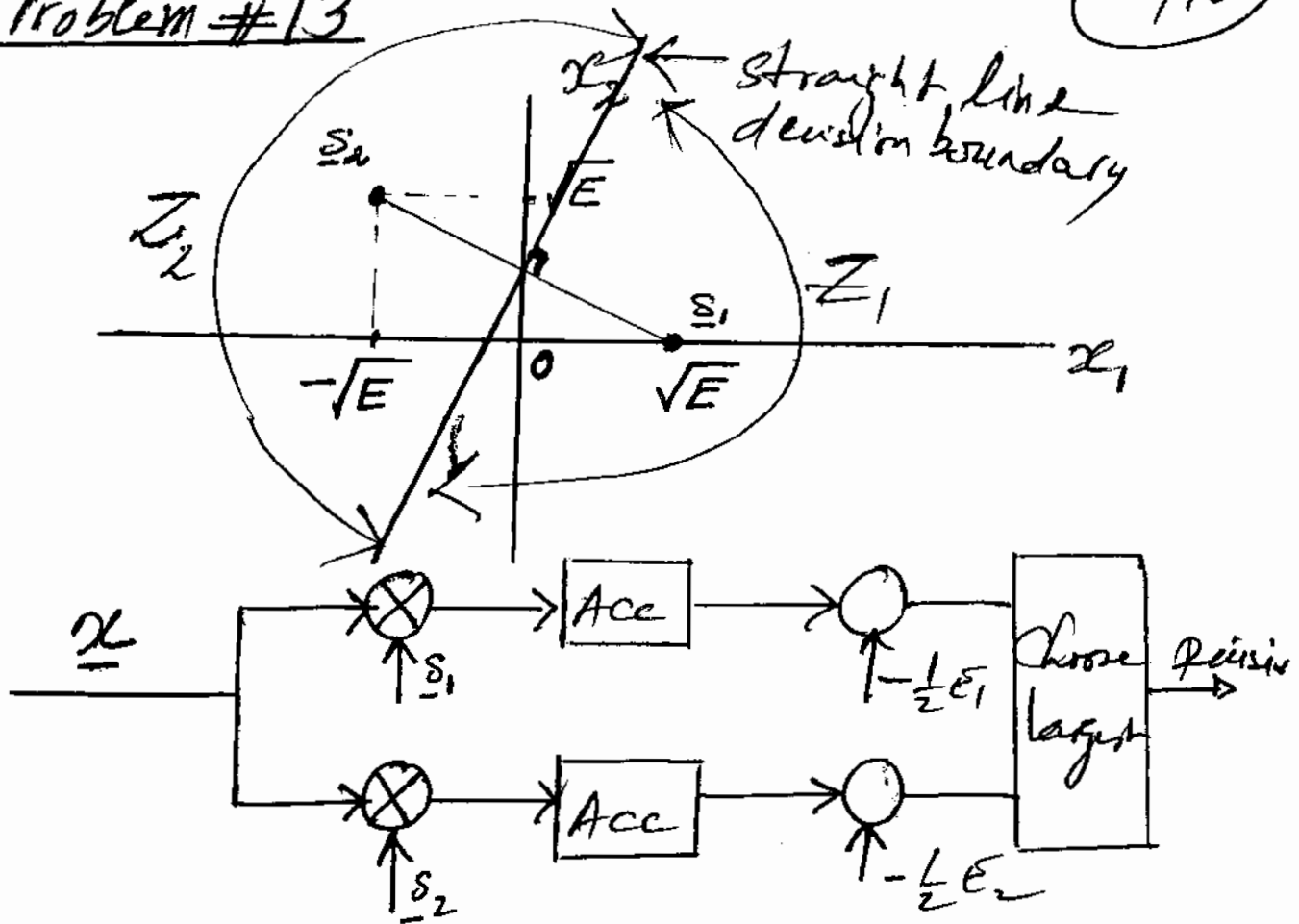
$$\phi_2(t) = \sqrt{\frac{2}{T}} \cos(\omega_c t - \frac{\pi}{2}),$$

$$= \sqrt{\frac{2}{T}} \sin(\omega_c t), \quad 0 \leq t \leq T.$$

Hence, 2 correlators need to be used in the reception of the given 4 signals in additive white and Gaussian noise.

Problem #13

(10/10)



$$\underline{x} \cdot \underline{s}_1 - \frac{1}{2} E_1 = \sqrt{E} x_1 - \frac{1}{2} E \quad (1)$$

$$\underline{x} \cdot \underline{s}_2 - \frac{1}{2} E_2 = -\sqrt{E} x_1 + \sqrt{E} x_2 - \frac{1}{2} (2E) \quad (2)$$

The straight line between the decision regions is obtained by equating (1) and (2).

$$\Rightarrow 2\sqrt{E} x_1 + \frac{1}{2} E = \sqrt{E} x_2$$

$$\Rightarrow x_2 = 2x_1 + \frac{1}{2} \sqrt{E}$$