

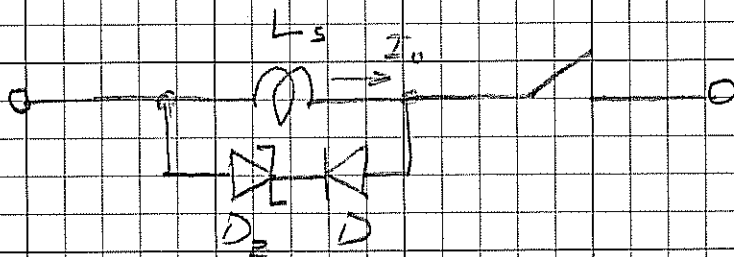
EECE 473 Power Electronics  
Midterm Exam

April 14, 2010

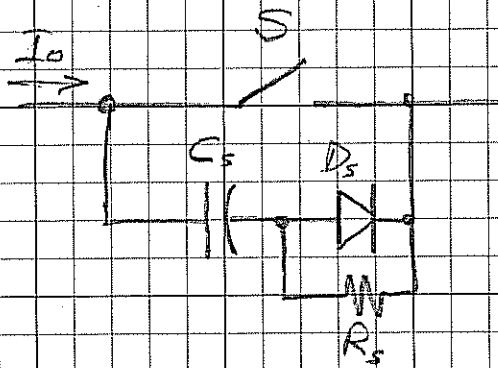
1. a) Snubber circuits protect devices against high  $di/dt$  and high  $dv/dt$  which are turn-on and turn off snubbers, respectively. A turn-on snubber is essentially an inductance inserted in series with the switching device and its value is calculated from:

$$L_s = V_s \left( \frac{di}{dt} \right)_{dev}^{-1}$$

So if the supply voltage is 100V and the allowed rate of rise of device  $(di/dt)_{dev} = 10^8 \text{ A/s}$ , then  $L_s = 1 \mu\text{H}$ . When the device is switched off a path for the current in  $L_s$  must be provided as shown:



The turn off snubber controls the rate of rise of voltage across a device by inserting a capacitance as shown:



When S turns off with a load current  $I_0$   
The voltage rise across it controlled by

$C_S =$

$$C_S = I_0 \left( \frac{dV}{dt} \right)_{\text{dev}}^{-1}$$

For a current of 10 A and  $(dV/dt)_{\text{dev}} = 10^5 \text{ V/s}$   
 $C_S = 10^{-4} \text{ F} = 100 \mu\text{F}$

b)

BJT require a continuous current strong enough to cause the device to operate in the saturation region. Usually we over-drive the BJT by a factor of 50 to 100% (i.e. ODF = 0.5 to 1)

$$I_B = \frac{I_C \text{ ODF}}{\beta}$$

To enhance turn-on we can shape the base current to provide a large initial pulse allowing for a quick charge of the base to emitter capacitance ( $C_{be}$ ).

MOSFETS require a voltage signal which is continuous and higher than the threshold voltage given in the gate-to-source characteristic.

But the gate supply must also have strong current sourcing ability to charge the gate to source capacitance quickly. Current sink capability of the gate drive is also desirable to allow quick  $C_{gs}$  discharge and turn off of the MOSFET.

A GTO requires a positive current pulse to turn it on and a negative pulse to turn it off. The negative pulse usually has an amplitude equal to about one quarter of the main thyristor current. The GTO is sensitive to noise appearing between gate and cathode and to minimize sensitivity a continuous positive current, but small, is usually supplied.

There are two stages in a drive circuit: the signal processing stage to generate the current or voltage signal wave and a second interface stage to amplify the signal and apply it to the device. Frequently we need to isolate the device from the drive circuit

using a signal transformer or optocoupler to generate identical signals driving devices with different common points.

2. a) When  $Q$  is turned on a voltage pulse appears across primary and is reflected on to secondary. A current will circulate on secondary and is limited by  $R_g$ ; the current entering the thyristor gate and the voltage between gate and cathode should larger than  $I_{GT}$  and  $V_{GT}$  specified in the data sheet of the thyristor. The duration of the current pulse should longer than the minimum turn-on time of the thyristor; this is controlled by the turn-on time of the transistor  $Q$ . The resistance  $R_{gk}$  is to shut noise appearing between gate and cathode and its value should much larger (10 times) than  $V_{GT}/I_{GT}$ . Diode  $D_2$  is to prevent current from being extracted from gate when the magnetizing inductance is discharging. When  $Q$  is turned off the magnetizing inductance discharges its energy through  $D_1$  and  $D_2$  is used to control the discharge time.  $R_p$  is to limit the current through  $Q$  and the transformer is to provide isolation between the drive circuit and the thyristor voltage.

b) The Thyristor is subjected to 380V rms or  $380 \times \sqrt{2} = 537.3V$  peak, So an appropriate selection would be the 2N6508. But if we want to keep a 20% safety margin for inadvertent overvoltages, then  $537.3 \times 1.2 = 644.8V$  should be considered. So it seems safer to use the 2N6509.

To allow for a wide range of operation we will design for an  $I_{GT} = 75mA$  ( $-40^{\circ}C$ ) and a gate trigger voltage of 1.5V ( $V_{GT}$ ). So the gate-trigger resistance is  $R_{GT} = 1.5/0.075 = 20\Omega$ .

$R_{GK}$  is selected to be much greater than  $R_{GT}$  so  $R_{GK} = 220\Omega$ .

Current on transformer secondary is:

$$I_s = \frac{0.075 + 1.5}{220} = 0.082A = 82mA$$

If we allow for 1V drop across  $D_2$ , for a resistance

$R_G = 22\Omega$  we obtain a secondary voltage of =

$$V_s = 1.5 + 1 + 22 \times 0.082 = 4.3V$$

c) Since the secondary voltage is well below the voltage supply of the driving transistor, then 1:1 turns ratio could be satisfactory. The number of turns is selected to be 4.

The transformer core area is given by:

$$A_c = \frac{V_p t_{on}}{N_p B_s} = \frac{4.3 \times 3 \times 10^{-6}}{4 \times 1.5} = 2.15 \times 10^{-6} \text{ m}^2 = 2.15 \text{ mm}^2$$

A suitable wire is AWG 24 ( $\approx 0.5 \text{ mm } \phi$ ) with maximum ampere of 0.577 A. So the opening of the core should be at least:

$$\frac{8 \times 0.51^2}{4} \times \pi \times (2) \approx 3.3 \text{ mm}^2$$

The T 6x3x4 would an opening of  $7.07 \text{ mm}^2$ , which would give plenty of room to make the turns.

This core has an area of  $A_c = \frac{6-3}{2} \times 1 = 1.5 \text{ mm}^2$  and a core length  $l_c = \left(\frac{6+3}{2}\right) \times \pi = 14.14 \text{ mm}$ .

d) The magnetizing inductance is given by =

$$L_{\mu} = \frac{\mu \times A_c \times N_p^2}{l_c} = \frac{4\pi \times 2 \times 10^4 \times 6 \times 10^{-6} \times 16}{10^7 \times 19.14 \times 10^{-3}} \Rightarrow$$

$$L_{\mu} = 341 \mu\text{H}$$

The magnetizing current is:  $I_{\mu} = \frac{V_p \times 10^3}{L_{\mu}}$

$$I_{\mu} = \frac{4.3 \times 3 \times 10^{-6}}{341 \times 10^{-6}} = 0.0378 \text{ A}$$

The primary current is 0.082 A, so the total current flowing in the transistor is:

$$I_c = 0.082 + 0.0378 = 0.12 \text{ A} = 120 \text{ mA}$$

The value of  $R_p$  is determined using KVL =

$$V_{cc} = I_c R_p + V_p + V_{ce(\text{SAT})} \Rightarrow$$

$$R_p = \frac{V_{cc} - V_p - V_{ce(\text{SAT})}}{I_c} = \frac{12 - 4.3 - 0.5}{0.12} = 60 \Omega$$

So a  $R_p = 56 \Omega$  is selected.

The current in the base needed to drive the transistor at the edge of saturation is  $I_B = \frac{I_c}{\beta} = \frac{120}{75} = 1.6 \text{ mA}$

with a  $\text{ODF} = 2$ ,  $I_{B(\text{ST})} = 1.6 \times 2 = 3.2 \text{ mA}$ .

$$S_o \quad R_B = \frac{5 - 0.0032 \times 100 - 0.7}{0.0032} = 1244 \Omega = 1.2 \text{ k}\Omega$$



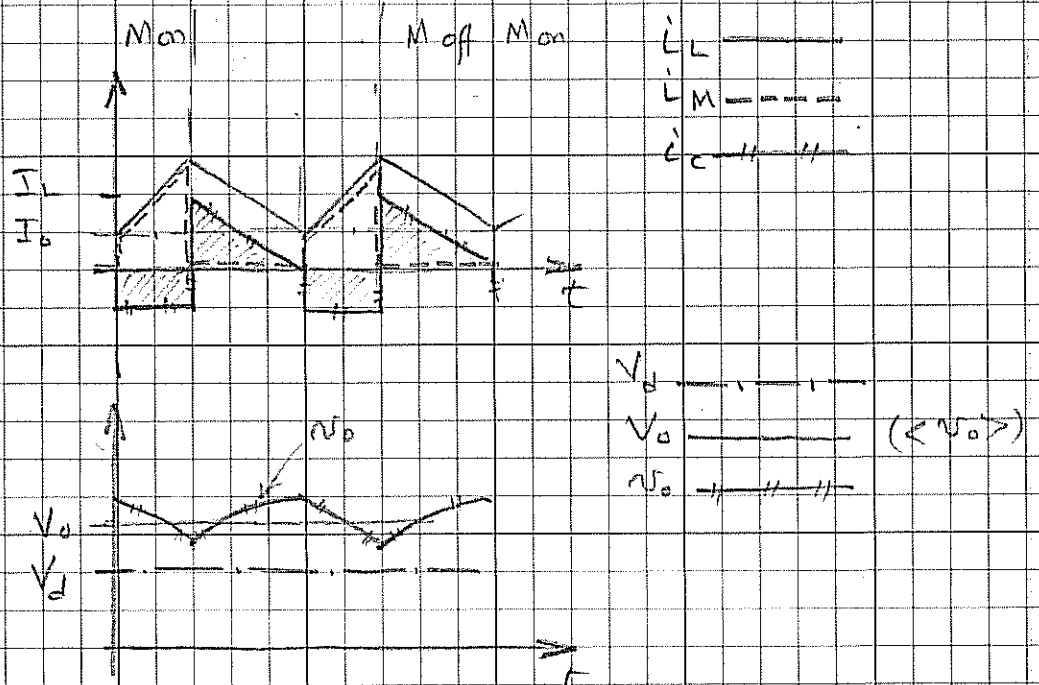
3.

a) The boost converter has two modes of operations:

i) when  $M$  is turned on the inductor  $L$  charges and  $i_L$  increases. Diode  $D$  is reverse biased by the capacitor ( $V_{DS}$  is negligible). The load is provided with energy from capacitor  $C$  and  $i_C$  decreases.

ii) When  $M$  is turned off the energy in the inductor is transferred to  $C$  and the load through the Diode. Note that  $V_o > V_d$  since this is a boost converter.

The waveforms are shown below.





b) Range of duty cycle operation:

$$V_d = 36 \quad V_o C \{40, 80\}$$

$$D_1 = 1 - \frac{36}{40} = 0.1 \quad \text{and} \quad D_2 = 1 - \frac{36}{80} = 0.55$$

$$I_{LB} = \frac{\Delta I_L}{2} = \frac{V_d D}{2 f_s L} \quad \text{with} \quad I_{LB} = \frac{I_o}{1-D}$$

$$L = \frac{V_d (1-D) D}{2 I_o f_s} = \frac{36 \times (1-0.55) 0.55}{2 \times 2 \times 25 \times 10^3} = 89 \times 10^{-6}$$

We will use  $L = 100 \mu\text{H}$  to ensure continuous conduction.

The capacitance is given by:

$$C = \frac{I_o D}{\Delta V_o f_s} = \frac{8 \times 0.55}{0.05 \times 80 \times 25 \times 10^3} = 44 \mu\text{F} (\sim 50 \mu\text{F})$$

The peak transistor current is equal to the peak inductor current:

$$I_m(\text{peak}) = I_L + \frac{\Delta I_L}{2}$$

$$I_L = \frac{I_o}{1-D} = \frac{8}{1-0.55} = 17.8 \text{ A}$$

$$\frac{\Delta I_L}{2} = \frac{0.55 \times 36 (1-0.45)}{2 \times 25 \times 10^3 \times 100 \times 10^{-6}} = 1.78 \text{ A}$$

$$I_m(\text{peak}) = 19.6 \text{ A}$$

The peak voltage is  $80 + 1 + 0.05 \times 80 = 85 \text{ V}$

The IRF150 has a continuous current rating of 24A and back  $V_{DS}$  of 100V, at 100°C. The forward voltage drop is slightly less than 1V ( $I_{DS} \times R_{DS}$ )!

The turn on time (delay plus rise) is 125ns and the turn off time is 300ns. So from power rating and switching speed the IRF150 is suitable.

- c) This is a complementary drive circuit when A is high,  $Q_1$  is turned on and the gate-source capacitance of MOSFET (M) is charged from supply  $V_{CC}$  via  $R_1$ ; when A is low  $Q_2$  becomes a low impedance path and  $C_{gs}$  of M discharges to ground. Diode D provides a path to discharge the capacitance of  $Q_1$  ( $C_{BE}$ ) when  $V_A$  goes low.

To have fast turn on time of the MOSFET (IRF150) we will allow an initial current pulse of 600mA.

So:

$$R_1 = \frac{V_{CC} - V_{BE(SAT)}}{I_{C(max)}} = \frac{12 - 0.5}{0.6} = 19.7 \Omega$$

We can select 22 $\Omega$ , which is slightly higher. But we could also select an 18 $\Omega$  resistor, which will give slightly higher current. This

is possible because the current is a pulse and thus not continuous. To be sure we need to refer to the data sheet of the 2N2222A. The time needed to charge the capacitance to 110 nC is  $\sim 110/0.64 = 172$  ns.

$R_2$  is obtained from:

$$I_{\text{max}} = \frac{V_{\text{gs}}(0)}{R_2} \Rightarrow R_2 = \frac{12}{0.2} = 60 \Omega$$

So  $R_2$  is selected as  $56 \Omega$

The value of  $R_B$  is obtained as follows:

First calculate the base current of  $Q_1$  with an ODF of 1.5

$$I_B = \frac{I_C}{\beta} \times \text{ODF} = \frac{600}{75} \times 1.5 = 12 \text{ mA}$$

$$\text{So } R_B = \frac{12 - 0.8}{12 \text{ (mA)}} = 12 \times 0.1 = 0.83 \text{ k}\Omega \text{ (820}\Omega\text{)}$$

This will give an ODF for  $Q_2$  of:

$$\text{ODF} = \frac{\beta I_B}{I_C} = \frac{75 \times 12}{200} = 4.5$$

which is rather high. To avoid this we can have separate base resistances for  $Q_1$  and  $Q_2$ .