CMPS 373: Parallel Computing

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Final Exam

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Name:

Duration: 90 minutes

Question 1 (60pts)

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Let A be a sparse $m \times m$ matrix and B a dense $m \times n$ matrix with $m \ge n$. Consider the matrix-matrix multiplication C = AB.

- (a) What is the time complexity of a straightforward sequential algorithm?
- (b) Choose distributions for A, B, and C and formulate a corresponding parallel algorithm. Motivate your choices of any distribution you adopt.
 - (c) Analyse the time complexity of the parallel algorithm.

Question 2 (40pts)

The Conjugent Gradient (CG) method is an iterative method for solving a symmetric positive definite linear system of equations $A\mathbf{x} = \mathbf{b}$. (A matrix A is **positive definite** if $\mathbf{x}^T A\mathbf{x} > 0$ for all $\mathbf{x} \neq \mathbf{0}$.)

The algorithm computes a sequence of approximations \mathbf{x}^k , k = 0, 1, 2, ..., that converges towards the solution \mathbf{x} . The algorithm is usually considered converged when $||\mathbf{r}^k|| \le \epsilon_{conv}||\mathbf{b}||$, where $\mathbf{r}^k = \mathbf{b} - A\mathbf{x}^k$. Recall that for a vector $\mathbf{x} = (x_1, x_2, ..., x_n)$, the (Euclidean) norm is given by $(x_1^2 + x_2^2 + ... + x_n^2)^{1/2}$.

A sequential CG algorithm is given on the next page ¹.

- (a) Design a parallel CG algorithm based on the sparse matrix-vector multiplication discussed in class. How do you distribute the various vectors and matrix A? Motivate your design choices.
 - (b) Analyse the time complexity of your algorithm.



¹All bold-face variables denote vectors, and non-bold ones denote scalars

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input: A: sparse n \times n matrix,
              b: dense vector of length n.
output: x: dense vector of length n, such that Ax \approx b.
\mathbf{x} := \mathbf{x}^0; { initial guess }
k := 0; \{ \text{ iteration number } \}
\mathbf{r} := \mathbf{b} - A\mathbf{x};

\rho := ||\mathbf{r}||^2;

while \sqrt{\rho} > \epsilon_{conv} ||\mathbf{b}|| \& \& k < k_{max} \mathbf{do}
              if k = 0 then
                       \mathbf{p} := \mathbf{r};
              else
                       \beta := \rho/\rho_{old};
                        \mathbf{p} := \mathbf{r} + \beta \mathbf{p};
              \mathbf{w} := A\mathbf{p};
              \gamma := \mathbf{p^T} \mathbf{w};
              \alpha := \rho/\gamma;
              \mathbf{x} := \mathbf{x} + \alpha \mathbf{p};
              \mathbf{r} := \mathbf{r} - \alpha \mathbf{w};

\rho_{old} := \rho

              \rho := ||\mathbf{r}||^2;
              k := k + 1;
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