

1) (16 points) Use Gauss-Jordan elimination to solve the following system of equations:

$$x_1 + x_2 + 3x_3 - x_4 = 0$$

$$x_1 - x_2 - x_3 - x_4 - 2x_5 = 4$$

$$x_2 + 2x_3 + 2x_4 - x_5 = 0$$

$$2x_1 - x_2 + x_4 - 6x_5 = 9$$

$$\begin{bmatrix} 1 & 1 & 3 & -1 & 0 & 0 \\ 1 & -1 & -3 & -1 & -2 & 0 \\ 0 & 1 & 2 & 2 & -1 & 0 \\ 2 & -1 & 0 & 1 & -6 & 9 \end{bmatrix} \xrightarrow{\begin{matrix} -1 \\ -2 \end{matrix}}$$

$$\begin{bmatrix} 1 & 1 & 3 & -1 & 0 & 0 \\ 0 & -2 & -4 & 0 & -2 & 4 \\ 0 & 1 & 2 & 2 & -1 & 0 \\ 0 & -3 & -6 & 3 & -6 & 9 \end{bmatrix} \xrightarrow{\begin{matrix} -1/2 \\ -1/3 \end{matrix}}$$

$$\begin{bmatrix} 1 & 1 & 3 & -1 & 0 & 0 \\ 0 & 1 & 2 & 0 & 1 & -2 \\ 0 & 0 & 0 & 2 & -2 & 2 \\ 0 & 0 & 0 & 3 & -3 & 3 \end{bmatrix} \xrightarrow{\begin{matrix} \times 1/2 \\ \times 1/3 \end{matrix}}$$

no need

$$\begin{bmatrix} 1 & 1 & 3 & -1 & 0 & 0 \\ 0 & 1 & 2 & 0 & 1 & -2 \\ 0 & 0 & 0 & 1 & -1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{\begin{matrix} -1 \\ -1 \end{matrix}}$$

free variables

Let x_5, x_2 free variables let $x_5 = s, x_2 = t$

2) (15 points) Discuss, according to the values of k , the nature of the solutions of the system whose augmented matrix is below. Then, solve the system whenever possible.

$$-2 \left(\begin{array}{ccc|c} 1 & 0 & 2k & 1 \\ 0 & 1 & 0 & 2 \\ 2 & -1 & k^2 & k \end{array} \right) \rightarrow \left[\begin{array}{ccc|c} 1 & 0 & 2k & 1 \\ 0 & 1 & 0 & 2 \\ 0 & -1 & 2k-k^2 & k-2 \end{array} \right]$$

$$\left[\begin{array}{ccc|c} 1 & 0 & 2k & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & -4k+k^2 & k \end{array} \right]$$

$$2k - 4k^2 = 2k(1 - 2k) \\ k(k-4)$$

* If $k=0$ then infinitely many solutions:
 → free variable.

let $x_3 = r$, $x_2 = 2$

$$x_1 = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ r \end{pmatrix}$$

* If $k=4$ then the third row will become $0 \ 0 \ 0 \ 0$

Then no solution
 Inconsistent system

* If $k \neq 4 \neq 0$ unique solution.

(15)

$$\left[\begin{array}{ccc|c} 1 & 0 & 2k & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & \frac{k-2}{k-4} \end{array} \right]$$

$$x_3 = \frac{k-2}{k-4}, \quad x_2 = 2$$

$$x_3 = \frac{k}{k-4} \rightarrow \begin{pmatrix} 1 \\ 2 \\ \frac{k}{k-4} \end{pmatrix}$$

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ \frac{k}{k-4} \end{pmatrix}$$

$$x_1 = \frac{1 - 2k}{k-4}$$

$$= \frac{k-4-2k}{k-4} = \frac{-k-4}{k-4}$$

$$\begin{aligned} &= \frac{1-2k}{1-2k} \\ &= \frac{1-3k}{1-2k} \end{aligned}$$

3) (15 points) Consider the matrix $A = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 3 \\ 0 & 0 & 1 \end{bmatrix}$.

a) (7 points) Find elementary matrices E_1 and E_2 such that $E_2 E_1 A = I$.

$$\begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 3 \\ 0 & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 3 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$E_1 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$E_2 = \begin{bmatrix} 1 & 0 & -3 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

b) (8 points) Use part (a) to express the matrix A as a product of two elementary matrices.

E_2 and E_1 invertible. The $E_2 E_1$ also invertible.

$$E_2 E_1 A = I \quad \text{Then } (E_2 E_1)^{-1} E_2 E_1 A = (E_2 E_1)^{-1} I$$

$$A = E_1^{-1} E_2^{-1} I = E_1^{-1} E_2^{-1}$$

$$E_1^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$E_2^{-1} = \begin{bmatrix} 1 & 0 & 3 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 3 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

(15)

4) (14 points)

a) (7 points) Let $A = \begin{bmatrix} 1 & -1 & 1 \\ 2 & -1 & 0 \\ 1 & -2 & 3 \end{bmatrix}$. Find A^{-1} or prove that A is not invertible.

$$\begin{array}{l} \left[\begin{array}{ccc|ccc} 1 & -1 & 1 & 1 & 0 & 0 \\ 2 & -1 & 0 & 0 & 1 & 0 \\ 1 & -2 & 3 & 0 & 0 & 1 \end{array} \right] \xrightarrow{\substack{R_2 - R_1 \\ R_3 - R_1}} \left[\begin{array}{ccc|ccc} 1 & -1 & 1 & 1 & 0 & 0 \\ 0 & 1 & -1 & -1 & 1 & 0 \\ 0 & -1 & 2 & -1 & 0 & 1 \end{array} \right] \\ \left[\begin{array}{ccc|ccc} 1 & -1 & 1 & 1 & 0 & 0 \\ 0 & 1 & -1 & -1 & 1 & 0 \\ 0 & -1 & 2 & -1 & 0 & 1 \end{array} \right] \xrightarrow{R_3 + R_2} \left[\begin{array}{ccc|ccc} 1 & -1 & 1 & 1 & 0 & 0 \\ 0 & 1 & -1 & -1 & 1 & 0 \\ 0 & 0 & 1 & -2 & 1 & 1 \end{array} \right] \\ \left[\begin{array}{ccc|ccc} 1 & -1 & 1 & 1 & 0 & 0 \\ 0 & 1 & -1 & -1 & 1 & 0 \\ 0 & 0 & 1 & -2 & 1 & 1 \end{array} \right] \xrightarrow{R_1 + R_2} \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 1 & -1 & -1 & 1 & 0 \\ 0 & 0 & 1 & -2 & 1 & 1 \end{array} \right] \end{array}$$

So A is not invertible since it cannot be reduced to I .

THE DEBATE

b) (7 points) Find the matrix X such that:

$$\begin{bmatrix} -5 & 2 \\ 3 & -1 \end{bmatrix} X = \begin{bmatrix} 2 & 0 & -1 \\ 3 & -5 & 0 \end{bmatrix}$$

$$A = \begin{bmatrix} -5 & 2 \\ 3 & -1 \end{bmatrix}$$

$$A^{-1} = \frac{1}{5-6} \begin{bmatrix} -1 & -2 \\ -3 & -5 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 3 & 5 \end{bmatrix}$$

$$AX = B$$

$$\underbrace{A^{-1}}_I AX = A^{-1}B \rightarrow X = A^{-1}B$$

$$X = \begin{bmatrix} 1 & 2 \\ 3 & 5 \end{bmatrix} \begin{bmatrix} 2 & 0 & -1 \\ 3 & -5 & 0 \end{bmatrix} = \begin{bmatrix} 8 & -10 & -1 \\ 21 & -25 & -3 \end{bmatrix}$$

5) (6 points) Prove the following theorem: If $A\vec{x} = \vec{b}$ is a system of linear equations, then the system has either no solutions, exactly one solution, or infinitely many solutions.

~~1) $\forall A, \vec{b}$~~
The problem can be solved if we show that $A\vec{m} = \vec{b}$ has infinitely many solutions.

Let m_1, m_2 be solutions for $A\vec{m} = \vec{b}$, with $\vec{x}_1 \neq \vec{x}_2$.

$$\text{Then } A\vec{m}_2 - A\vec{m}_1 = A(\vec{m}_2 - \vec{m}_1) = \vec{b} - \vec{b} = \vec{0}$$

So $\vec{m}_2 - \vec{m}_1$ is a solution of $A\vec{m} = \vec{0}$.

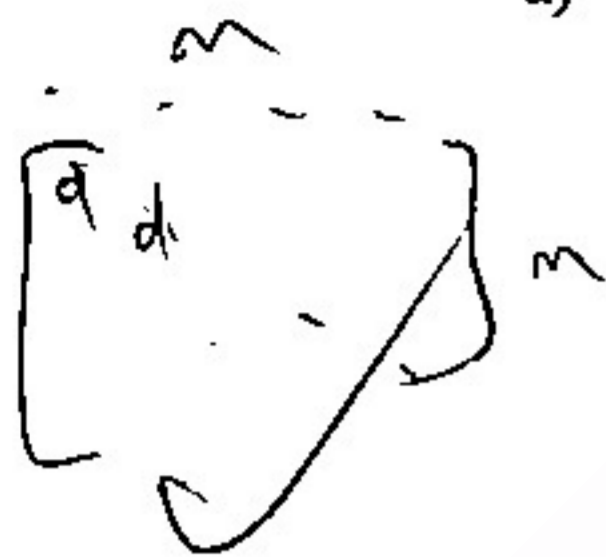
Let m_0 this solution, and K a scalar.

$$A(\vec{x}_1 + K\vec{m}_0) = A\vec{m}_1 + KA\vec{m}_0 = \vec{b} + K \times \vec{0} = \vec{b}$$

Then $\vec{m}_1 + K\vec{m}_0$ is a solution for the sys. $A\vec{m} = \vec{b}$ or K may have many ~~values~~ values.
Then the system has infinitely many solutions.

6) (16 points) Let A be an $n \times n$ matrix. Prove each of the following statements:

a) (4 points) If A is a diagonal matrix all of whose entries are d , then $\text{tr}(A) = nd$.



$$\text{tr}(A) = \sum A_{ii} = \underbrace{d + d + \dots + d}_{n \text{ terms}} = nd$$

The trace is the sum of the diagonal entries since none of them is 0 and each entry is d . Then $\text{tr}(A) = nd$.

b) (4 points) $A - A^T$ is skew-symmetric.

$$(A - A^T)^T = A^T - (A^T)^T = A^T - A = -(A - A^T)$$

Then $A - A^T$ is skew-symmetric.

c) (4 points) If A is invertible and $k \neq 0$ is a scalar, then kA^n is invertible and

$$(kA^n)^{-1} = \frac{1}{k} A^{-n}$$

If A is invertible then A^{-1} exists.

$$(A^{-1})^n \cdot A^n = (A^{-1} \cdot A)^n = I^n = I$$

$$A^n \cdot (A^{-1})^n = (A \cdot A^{-1})^n = I^n = I$$

The inverse of A^n is $(A^{-1})^n$.

A^n is invertible then kA^n is invertible.

$$(kA^n) \cdot \frac{1}{k} A^{-n} = \frac{k}{k} A^n (A^{-1})^n = \frac{k}{k} A^n (A^{-1})^n = I$$

d) (4 points) Let I be the $n \times n$ identity matrix. Then $IA = A$.

If A is $n \times n$ matrix.

Let $B = IA$

$$b_{ij} = \sum I_{im} a_{mj} = I_{i0} a_{0j} + \dots + I_{in} a_{nj}$$

$$= I_{ii} a_{ij} = 1 \cdot a_{ij} = a_{ij}$$

So $B = IA$ is equal to A .

IA is an $n \times n$ matrix because we have same size $n \times n$ and same entries.

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7) (18 points) Let A and B be two $n \times n$ matrices. Prove each of the following statements.

a) (4 points) If A and B are both invertible, then AB is invertible and $(AB)^{-1} = B^{-1}A^{-1}$.

$AB \times B^{-1}A^{-1} \Rightarrow A \cdot I \cdot A^{-1} = A A^{-1} = I$
 $(B^{-1}A^{-1})(AB) = B^{-1}(A^{-1}A)B = B^{-1}B = I$
 Then AB is invertible and $(AB)^{-1} = B^{-1}A^{-1}$

b) (4 points) If A is invertible and B is row-equivalent to A , then B is invertible.

B row equivalent to A then $E_n E_{n-1} \dots E_2 E_1 \cdot B = A$
 The elementary matrices is ~~an~~ invertible matrices. So product of

$$(E_n E_{n-1} \dots E_2 E_1)^{-1} (E_n E_{n-1} \dots E_2 E_1) B = (E_n E_{n-1} \dots E_2 E_1)^{-1} A$$

c) (6 points) Let $A\vec{x} = \vec{0}$ be a homogeneous system of linear equations and let B be invertible. Show that if $A\vec{x} = \vec{0}$ has only the trivial solution, then $(BA)\vec{x} = \vec{0}$ has only the trivial solution.

If $A\vec{x} = \vec{0}$ has only the trivial solution then A is invertible or B is invertible. Then BA is product of 2 invertible matrices is invertible.

Then $(BA)\vec{x} = \vec{0}$ will have only the trivial solution.

Then B of $E_n E_{n-1} \dots E_1$
 A is invertible A
 BA is product of 2 invertible matrices is invertible

d) (4 points) A square matrix M is said to be orthogonal if $MM^T = I$. Show that if A and B are both orthogonal, then AB is also orthogonal.

A is orthogonal then $AA^T = I$ ✓

B is orthogonal then $BB^T = I$ ✓

$$AB \times (AB)^T = A \underbrace{B \times B^T}_I A^T = A I A^T = A A^T = I$$

$\frac{1}{2} A$ is orthogonal.

Then AB is also orthogonal

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