

Virtual Function and Polymorphism allow the design and implementation of systems that are easily extensible...

Programs written to generically process objects of all existing classes in a hierarchy...

This can be achieved by taking the advantage of the “*pointer to derived class*” compatibility with a “*pointer to its base class*”...

```
<Pointer-to-base-class> = <Pointer-to-derived-class>
<Pointer-to-base-class> = &<Object-of-derived-class>
```

As seen earlier, a *pointer* to the base-class can point to any object of its derived classes without the need of explicit casting...

The same rule applies for a base-class *reference* to a derived object...

Lets consider the following scenario...

```
#include <iostream.h>
class pet {
public:
    void speak() {cout << "can't speak \n";}
};
class dog : public pet {
public:
    void speak() { cout << "woofffff! \n"; }
};
class cat : public pet {
public:
    void speak() { cout << "meawwww! \n"; }
};
class bird : public pet {
public:
    void speak() { cout << "squeekkk! \n"; }
};
```

```
void main() {
    dog spike;
    cat tom;
    bird tweety;
    pet *cage= &tom ;
    spike.speak();
    tweety.speak();
    tom.speak();
    cage->speak();[B]
    static_cast<bird*>(cage)->speak();[B]
}
```

What about this scenario ???...

```
void main() {
    pet *cage[3];
    cage[0] = new dog;
    cage[1] = new cat;
    cage[2] = new bird;
    cage[1]->speak();[B]
    static_cast<bird*>(cage[1])->speak();[B]
}
```

A solution !!!...

Virtual Functions

```
#include <iostream.h>
class pet {
public:
    virtual[DANS] void speak() {cout << "can't speak \n";}
};
class dog : public pet {
public:
    void speak() { cout << "woofffff! \n"; }
};
class cat : public pet {
public:
    void speak() { cout << "meawwww! \n"; }
};
class bird : public pet {
public:
    void speak() { cout << "squeekkk! \n"; }
};
```

```
void sayIt(pet &pRf, pet *pPr) {
    pRf.speak(); // Dynamic binding[DANS]
    pPr->speak(); // Dynamic binding[DANS]
}
```

```
void main() {
    bird tweety;
    pet *cage[3], &pRef_1 = tweety;
    cage[0] = new dog;
    cage[1] = new cat;
    cage[2] = new bird;

    cage[2]->speak(); // Dynamic binding[DANS1]
    cage[0]->speak();
    cage[1]->speak();

    pRef_1.speak(); // Dynamic binding[DANS1]
    tweety.speak(); // Static binding[DANS1]
    pet &pRef_2 = *cage[1];
    pRef_2.speak(); // Dynamic binding[DANS1]
    sayIt(*cage[0], cage[2]);
}
```

- By declaring function *speak* as *virtual*, and by using:
 - a base-class pointer that points to a derived-class object...
 - a base-class reference that references a derived class object...

the program will chose the correct derived class *speak* dynamically at run-time... **Dynamic binding**...

- When a virtual function is called by the object name using the “dot-operator”... the function called is the one *defined for* (or *inherited by*) the class of that particular object... **Static binding**...

More realistic scenario...

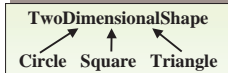
```
#include <iostream.h>
class Polygon {
public:
    void setPoly (int a, int b) {
        width = a;
        height = b;
    }
    virtual[DANS2] int area() {return 0;}
protected:
    int width, height;
};
class Rectangle: public Polygon {
public:
    int area () {return (width * height);}
};
class Triangle: public Polygon {
public:
    int area() {return (width * height / 2);}
};
```

```
void main () {
    Rectangle rect;
    Polygon *polyPtr[2], &polyRef = rect ;
    polyPtr[0] = new Rectangle;
    polyPtr[1] = new Triangle;
    polyPtr[0]->setPoly(4,5);
    polyPtr[1]->setPoly(2,50);
    polyRef.setPoly(1,30);
    cout << polyPtr[0]->area()[DANS3] << endl;
    cout << polyPtr[1]->area() << endl;
    cout << polyRef.area()[DANS4] << endl;
}
```

Abstract and Concrete Classes

• Abstract classes:

- Sole purpose is to provide a base class for other classes... Too generic to define real objects...
- *No objects* of an abstract base class can be instantiated... Syntax error...
- *Can have* pointers and references...



• Concrete classes:

- Classes that can instantiate objects...
- Provide specifics to make real objects... Square, Circle, etc...

- A class is made *abstract* by declaring one or more of its virtual function to be “*pure*”... A *pure virtual* function is one with an *initializer of =0* in its declarations...

```
class Polygon {
public:
    void setPoly (int a, int b) {
        width = a;
        height = b;
    }
    virtual int area() =0;
    virtual void print() const;[DANS5]
protected:
    int width, height;
};
```

```
#include <iostream.h>
class Polygon {
public:
    void setPoly (int a, int b) {
        width = a;
        height = b;
    }
    virtual int area() =0;
    virtual void print()[DANS5]=0;
protected:
    int width, height;
};
class Rectangle: public Polygon {
public:
    int area () {return (width * height);}
    void print()[DANS5] {
        cout << width << endl;
        cout << height << endl;
    }
};
class Triangle : public Polygon[DANS6] {
public:
    int area() {return (width * height / 2);}
};
```

```
void main () {
    Polygon poly;[DANS7]
    Rectangle rect;
    Triangle trgl;[DANS8]
}
```

Syntax Error...

Polymorphism

- From the Greek:

Poly → **Many**
Morph → **Shape**

- In OOP:

- Ability for objects of different classes (related by inheritance) to respond differently to the same function call...

- Polymorphism** is implemented via **virtual** functions...

- When a request is made through a **base class pointer** (or **reference**) to use a virtual function, C++ chooses the correct overridden function in the appropriate derived class associated with the object...

- Needless to say that **non-virtual** function behave in the same manner discussed in the inheritance chapter...

- If **non-virtual** member function defined in multiple classes and called from **base-class** pointer then the **base-class** version is used...
- If called from **derived-class** pointer then **derived-class** version is used...
- Non-polymorphic** behavior...

```
#include <iostream.h>

class Polygon {
public:
    void setPoly (int a, int b) {
        width = a;
        height = b;
    }
    virtual int area() { return 0;}
    void print() const {
        cout << "Width:" << width << " - "
            << "Height:" << height << endl;
    }
protected:
    int width, height;
};

class Rectangle: public Polygon {
public:
    int area() {return (width * height);}
};

class Triangle: public Polygon {
public:
    int area() {return (width * height / 2);}
    void print() const {
        cout << "Base:" << width << " - "
            << "Height:" << height << endl;
    }
};
```

```
void main() {
    Rectangle rect;
    Triangle trgl;
    Polygon *polyPtr,
        &polyRefR = rect,
        &polyRefT = trgl;

    rect.setPoly(10,2);
    trgl.setPoly(30,3);

    rect.print();
    trgl.print();
    cout << rect.area() << endl;
    cout << trgl.area() << endl;

    polyPtr = &trgl;
    polyPtr->print();
    cout << polyPtr->area() << endl;

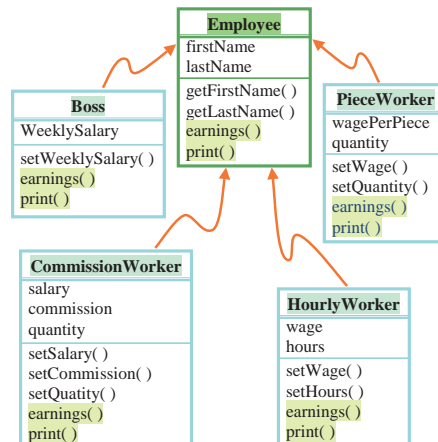
    polyPtr = &rect;
    polyPtr->print();
    cout << polyPtr->area() << endl;

    polyRefT.print();
    cout << polyRefT.area() << endl;

    polyRefR.print();
    cout << polyRefR.area() << endl;
}
}DAN09
```

Case Study: A Payroll system using Polymorphism

- Perform different payroll calculations for different types of employees (base class **Employee**):
 - Boss** - fixed weekly salary
 - CommissionWorker** - flat base salary + commission
 - PieceWorker** - paid according to items produced
 - HourlyWorker** - hourly wage + overtime



Virtual destructor

• Recall

```
#include <iostream.h>
class A {
public:
    A(int x = 0) {
        valA = x;
        cout << "Constructor: valA= "
              << valA << endl;
    }
    ~A() {
        cout << "Destructor: valA= "
              << valA << endl;
    }
private:
    int valA;
};

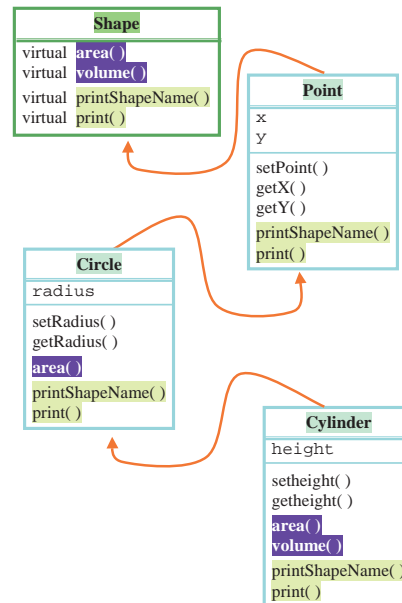
void main() {
    A *aPtr, aObj(5);
    aPtr = new A[2];
    delete [] aPtr;
}
```

- An object allocated using the *new* operator must be explicitly deallocated using the *delete* operator... It is at the deletion time that the destructors is called...

```
#include <iostream.h>
class basA {
public:
    basA (int a) { x = a; }
    virtual ~basA() {
        cout << "Base destructor... x = " << x << endl;
    }
protected:
    int x;
};
class drvA: public basA {
public:
    drvA(int a, int b) : basA(a) { y = b;}
    int getA() {return y;}
    void setA(int a) { y = a;}
    ~drvA() {
        cout << "Derived destructor... y = " << y << endl;
    }
private:
    int y;
};

void main() {
    basA *basPtr;
    drvA *drvPtr;
    drvPtr=new drvA(10, 20);
    delete drvPtr;
    drvPtr=new drvA(100, 200);
    basPtr = drvPtr;
    delete basPtr;
}
```

- Problem:
 - If a *base-class pointer* to a *derived object* is deleted, the *base-class destructor* will act on the object...
- Solution:
 - Declare a virtual base-class destructor to ensure that the appropriate destructor will be called

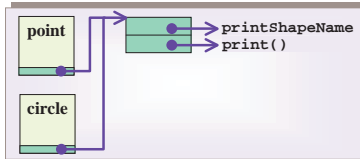
Case Study: Inheriting Interface and Implementation

Polymorphism, virtual Functions and Dynamic Binding “Under the Hood”

The fundamental idea behind polymorphism is that the compiler **does not know** which function to call **compile-time**...the appropriate function will be selected **run-time**....

A common implementation is the following...

- An *object* containing virtual member functions holds as its *first data member* a *hidden field*, pointing to an *array of pointers* containing the *addresses of the virtual member functions* ...



- The hidden data member is usually called the *vpointer*...
- The array of virtual member function addresses is called the *vtable*...
- Final Note:
 - Polymorphism requires some overhead...
 - Polymorphism is not used in STL (Standard Template Library) to optimize performance...