

Theorem 1.5.4

Let A and B be two square matrices having the same size $n \times n$ such that $BA = I$ (or $AB = I$) not necessarily both Then A is invertible with inverse B .

proof

Theorem 1.5.5

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let A & B be two square matrices having the same size $n \times n$
such that $A \cdot B$ is invertible then A & B are invertible matrices
proof

Determinants

All the matrices considered in this section are square matrices

definition 1.6.1

A determinant function is a real valued function of a square matrix variable

$$\text{i.e. } \det: \mathbb{T} \longrightarrow \mathbb{R}$$

set of square matrices

The determinant of a square matrix A is denoted by $\det(A)$ or $|A|$

$$A \longrightarrow \det(A)$$

definition 1.6.2 (Determinant of a 2×2 matrix)

The determinant of a 2×2 matrix $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$ denoted by $|A|$ or $\det(A)$ is given by the formula:

$$|A| = \det(A) = \begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$$

(a 2×2 matrix $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$ is invertible $\Leftrightarrow ad - bc \neq 0$)

section 1.4

example

$$\text{let } A = \begin{pmatrix} 3 & 1 \\ -2 & 2 \end{pmatrix} \quad B = \begin{pmatrix} 3 & 5 \\ 4 & 2 \end{pmatrix} \quad \text{find } |A| \text{ \& } |B|$$

answer

$$|A| = 3(2) - (1)(-2) = 6 + 2 = 8 \quad \& \quad |B| = 3(2) - 4(5) = 6 - 20 = -14$$

definition 1.6.3 (Minors & cofactors)

- (a) If A is a square matrix we define the minor of the entry A_{ij} denoted by M_{ij} to be the determinant of the submatrix that remains after the i th row & j th column are deleted from A
- (b) The cofactor of the entry A_{ij} denoted by C_{ij} is given by the formula $C_{ij} = (-1)^{i+j} M_{ij}$

example

If $A = \begin{pmatrix} 2 & 1 & -1 \\ 3 & 1 & 4 \\ 5 & -3 & 3 \end{pmatrix}$ find M_{11} , M_{23} , C_{23} & C_{31}

Answer

$$M_{11} = \begin{vmatrix} 1 & 4 \\ -3 & 3 \end{vmatrix} = 1(3) - (4)(-3) = 3 + 12 = 15 \quad M_{23} = \begin{vmatrix} 2 & 1 \\ 5 & -3 \end{vmatrix} = 2(-3) - 5(1) = -11$$

$$C_{23} = (-1)^{2+3} M_{23} = (-1)(-11) = 11$$

$$C_{31} = (-1)^{3+1} M_{31} = M_{31} = \begin{vmatrix} 1 & -1 \\ 1 & 4 \end{vmatrix} = 1(4) - 1(1) = 5$$

definition 1.6.4 (determinant of 3×3 and any $n \times n$ matrix along 1st row)

The determinant of the $n \times n$ matrix A computed by cofactor expansion along the 1st row is given by the formula

$$\det(A) = a_{11}C_{11} + a_{12}C_{12} + \dots + a_{1n}C_{1n} \text{ where } A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix}$$

\Rightarrow if $A = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix}$ is any 3×3 matrix then determinant of A

Computed by cofactor expansion along the 1st row is given by the formula $\det(A) = a_{11}C_{11} + a_{12}C_{12} + a_{13}C_{13}$

example

$$A = \begin{pmatrix} 1 & -1 & 0 \\ 1 & 1 & 1 \\ -1 & 0 & -1 \end{pmatrix} \quad B = \begin{pmatrix} 3 & 1 & 0 \\ -2 & -4 & 3 \\ 5 & 4 & -2 \end{pmatrix}$$

find $|A|$ & $|B|$

Answer

NB

Cofactors & Minors differ only in signs

if C is the matrix of cofactors of A with entries a_{ij} and corresponding cofactors C_{ij} & minors M_{ij} then

$$C = \begin{pmatrix} +M_{11} & -M_{12} & +M_{13} & \dots & + \\ -M_{21} & +M_{22} & -M_{23} & \dots & - \\ + & - & + & \dots & - \\ - & + & - & \dots & + \\ \dots & \dots & \dots & \dots & \dots \end{pmatrix}$$

alternating signs
The identity in any cofactor matrix starts with the sign (+ minor) since $C_{11} = +M_{11}$ and then for the other cofactors we use alternating signs.

Theorem 1.6.1

Let A be any $n \times n$ matrix then the determinant of A can be computed by cofactor expansion along any row or any column

along the i th row: $\det(A) = a_{i1}C_{i1} + a_{i2}C_{i2} + \dots + a_{in}C_{in}$

along the j th col: $\det(A) = a_{1j}C_{1j} + a_{2j}C_{2j} + \dots + a_{nj}C_{nj}$

example

find the determinant of $B = \begin{pmatrix} 3 & 1 & 0 \\ -2 & -4 & 3 \\ 5 & 4 & -2 \end{pmatrix}$ along 2nd col & 3rd row

answer

Smart choice (example)

find $\det(A)$ where $A = \begin{pmatrix} 1 & 0 & 0 & -1 \\ 3 & 1 & 2 & 2 \\ 1 & 0 & -2 & 1 \\ 2 & 0 & 0 & 1 \end{pmatrix}$

Answer

We can find the $\det(A)$ by cofactor expansion along any row or column but notice how much we save time in finding the determinant of the matrix A if we choose the 2nd column (i.e. the col or row with the most of zeros) instead of choosing 1st row or 1st col etc...

$$|A| = \underbrace{-0}_{0} \begin{vmatrix} \dots \end{vmatrix} + 1 \begin{vmatrix} 1 & 0 & -1 \\ 1 & -2 & 1 \\ 2 & 0 & 1 \end{vmatrix} - \underbrace{0}_{0} \begin{vmatrix} \dots \end{vmatrix} + \underbrace{0}_{0} \begin{vmatrix} \dots \end{vmatrix}$$

$$\Rightarrow |A| = \begin{vmatrix} 1 & 0 & -1 \\ 1 & -2 & 1 \\ 2 & 0 & 1 \end{vmatrix} = \underbrace{-0}_{0} + (-2) \begin{vmatrix} 1 & -1 \\ 2 & 1 \end{vmatrix} - \underbrace{0}_{0} = -2(1+2) = -6$$

cofactor expansion along 2nd col

definition 1.6.6 (triangular & diagonal matrix)

(a) A square matrix is called an upper triangular matrix iff all its entries below the main diagonal are zeros

$$\text{i.e. } a_{ij} = 0 \quad \forall i > j$$

(b) A square matrix is called a lower triangular matrix iff all its entries above the main diagonal are zeros

$$\text{i.e. } a_{ij} = 0 \quad \forall i < j$$

(c) A square matrix is called a diagonal matrix iff all the entries off the main diagonal are zeros.

$$\text{i.e. } a_{ij} = 0 \quad \forall i \neq j$$

examples

$$\begin{pmatrix} a_{11} & a_{12} & a_{13} & a_{14} \\ 0 & a_{22} & a_{23} & a_{24} \\ 0 & 0 & a_{33} & a_{34} \\ 0 & 0 & 0 & a_{44} \end{pmatrix} \text{ upper } \Delta \text{ matrix} \quad \begin{pmatrix} a_{11} & 0 & 0 & 0 \\ a_{21} & a_{22} & 0 & 0 \\ a_{31} & a_{32} & a_{33} & 0 \\ a_{41} & a_{42} & a_{43} & a_{44} \end{pmatrix} \text{ lower } \Delta \text{ matrix} \quad \begin{pmatrix} a & 0 & 0 & 0 \\ 0 & b & 0 & 0 \\ 0 & 0 & c & 0 \\ 0 & 0 & 0 & d \end{pmatrix} \text{ diag matrix}$$

Theorem 1.6.2

If A is an $n \times n$ triangular matrix then the determinant of A is the product of the entries on the main diagonal

(This is also true for diagonal matrix since diagonal matrix is upper & lower triangular at the same time)

proof

$$A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ 0 & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & a_{nn} \end{pmatrix} \text{ upper } \Delta \text{ matrix}$$

$$\det(A) = a_{11} \begin{vmatrix} a_{22} & a_{23} & \dots & a_{2n} \\ 0 & a_{33} & \dots & a_{3n} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & a_{nn} \end{vmatrix} \begin{matrix} \text{along 1st col} \\ \text{if expansion} \\ \text{along 1st col or last} \\ \text{of row} \end{matrix} = a_{11} a_{22} \begin{vmatrix} a_{33} & a_{34} & \dots & a_{3n} \\ 0 & a_{44} & \dots & a_{4n} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & a_{nn} \end{vmatrix} \begin{matrix} \text{etc} \\ \dots \end{matrix} = a_{11} a_{22} a_{33} \begin{vmatrix} a_{44} & \dots & a_{4n} \\ 0 & a_{55} & \dots & a_{5n} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & a_{nn} \end{vmatrix}$$

$$= a_{11} a_{22} a_{33} \dots a_{n-2} a_{n-1} \begin{vmatrix} a_{n-1} & a_{n-1} \\ 0 & a_{nn} \end{vmatrix} = a_{11} a_{22} a_{33} \dots a_{nn} \text{ (product entries on the main diagonal)}$$

Theorem 1.6.2

Let A be a square matrix

(a) if A has a row or column of zeros then $\det(A) = 0$

(b) $\det(A) = \det(A^T)$ (since \det can be found along any row or column)

Theorem 1.6.3 (properties of determinant)

Let A be a square matrix

(a) If two rows or columns of A are interchanged to produce a matrix B then $\det(B) = -\det(A)$

(b) If a row or column of A is multiplied by a constant k to produce a matrix B then $\det(B) = k \det(A)$

(c) If a multiple of one row or column of A is added to another to produce B then $\det(B) = \det(A)$

example

$$A = \begin{pmatrix} 0 & 1 & 3 & -1 \\ 2 & 4 & -6 & 1 \\ 0 & 3 & 9 & 2 \\ -2 & -4 & 1 & -3 \end{pmatrix}$$

Theorem 1.6.4

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Let A & B be $n \times n$ matrices and $k \in \mathbb{R}$, then:

(a) $\det(A \cdot B) = \det(A) \cdot \det(B)$

(b) $\det(kA) = k^n \det(A)$

(c) If A has 2 proportional rows (or columns) then $\det(A) = 0$

example

let $A = \begin{pmatrix} 1 & 2 \\ 3 & -2 \end{pmatrix}$ $B = \begin{pmatrix} 1 & -1 \\ 1 & 4 \end{pmatrix}$ find $\det(A \cdot B)$

1st way

$$\det(A \cdot B) = \det(A) \cdot \det(B) = ((-2) - 6)(4 - (-1)) = (-8)(5) = -40$$

2nd way

$$A \cdot B = \begin{pmatrix} 3 & 7 \\ 1 & -11 \end{pmatrix} \Rightarrow \det(A \cdot B) = -33 - 7 = -40$$

Remark 1

let A & B be two $n \times n$ matrices

$$\det(A \cdot B) = \det(A) \cdot \det(B) \text{ But!!! } \det(A+B) \neq \det(A) + \det(B)$$

see previous example

$$A+B = \begin{pmatrix} 2 & 1 \\ 4 & 2 \end{pmatrix} \quad \det(A+B) = 4 - 4 = 0 \neq -8 + 5 = 3 = \det(A) + \det(B)$$

Remark 2

Let A, B & C be 3×3 matrices that differ only in a single row or column saying the i th row or j th col where

$$(i\text{th row of } C) = (i\text{th row of } A) + (i\text{th row of } B)$$

or $(j\text{th col of } C) = (j\text{th col of } A) + (j\text{th col of } B)$

Then $\det(C) = \det(A) + \det(B)$

$$A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{ni} & a_{n2} & \dots & a_{nn} \end{pmatrix} \quad B = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ b_{21} & b_{22} & \dots & b_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{ni} & a_{n2} & \dots & a_{nn} \end{pmatrix} \quad C = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ (a_{21}+b_{21}) & (a_{22}+b_{22}) & \dots & (a_{2n}+b_{2n}) \\ \vdots & \vdots & \ddots & \vdots \\ a_{ni} & a_{n2} & \dots & a_{nn} \end{pmatrix}$$

$$\det(C) = (a_{21}+b_{21})C_{21} + \dots + (a_{2n}+b_{2n})C_{2n} = (a_{21}C_{21} + \dots + a_{2n}C_{2n}) + (b_{21}C_{21} + \dots + b_{2n}C_{2n}) = \det(A) + \det(B)$$

Theorem 1.6.5

A square matrix A is invertible if & only if $\det(A) \neq 0$

proof

Corollary 1.6.1

Let A be an invertible matrix then $\det(A^{-1}) = \frac{1}{\det(A)}$

proof

Theorem 1.6.6 (Cramer's rule)

Let $Ax=b$ be a linear system of n linear equations & n unknowns such that $\det(A) \neq 0$ (ie A invertible) then the system has a unique solution $x = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$ where $x_i = \frac{\det(A_i)}{\det(A)} \quad \forall i=1, \dots, n$.

& A_i is the matrix obtained by replacing the entries of the i th column of A by the entries of the constant matrix b

$$A_i = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1i-1} & \mathbf{b_1} & a_{1i+1} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2i-1} & \mathbf{b_2} & a_{2i+1} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \ddots & \vdots \\ a_{ni} & a_{n2} & \dots & a_{ni-1} & \mathbf{b_n} & a_{ni+1} & \dots & a_{nn} \end{pmatrix}$$

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example

solve the system $\begin{cases} x - y - 2z = 3 \\ x + 2y + 3z = 1 \\ 2x - 2y - 2z = -2 \end{cases}$ using Cramer's rule

answer

$$\underbrace{\begin{pmatrix} 1 & -1 & -2 \\ -1 & 2 & 3 \\ 2 & -2 & -2 \end{pmatrix}}_A \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 3 \\ 1 \\ -2 \end{pmatrix} \quad \det(A) = 1(-4+6) + 1(2-6) - 2(2-4) = 2 - 4 + 4 = 2$$

$$\text{let } A_1 = \begin{pmatrix} 3 & -1 & -2 \\ 1 & 2 & 3 \\ -2 & -2 & -2 \end{pmatrix} \quad A_2 = \begin{pmatrix} 1 & 3 & -2 \\ -1 & 1 & 3 \\ 2 & -2 & -2 \end{pmatrix} \quad A_3 = \begin{pmatrix} 1 & -1 & 3 \\ -1 & 2 & 1 \\ 2 & -2 & -2 \end{pmatrix}$$

$$|A_1| = 3(2) + 4 - 4 = 6 \quad |A_2| = 4 - 12 - 2(0) = -8 \quad |A_3| = 1(-2) + 1(0) + 3(2) = 4$$

$$\Rightarrow x = \frac{|A_1|}{|A|} = 3 \quad y = \frac{|A_2|}{|A|} = -4 \quad z = \frac{|A_3|}{|A|} = 2$$

Theorem 1.6.7

let A be a square matrix then the following are equivalent

- A is invertible
- $Ax=b$ has a unique solution $x=A^{-1}b$ for any $n \times 1$ matrix b
- $Ax=0$ has only the trivial solution
- the reduced row echelon form of A is I (ie A is row equivalent to I)
- the determinant of the matrix A : $\det(A) \neq 0$

Supp exercises

[1] Determine Conditions on b_1, b_2 & b_3 for the following systems to be consistent.

system 1
$$\begin{cases} x_1 + x_2 + 2x_3 = b_1 \\ x_1 \quad \quad + x_3 = b_2 \\ 2x_1 + x_2 + 3x_3 = b_3 \end{cases}$$

system 2
$$\begin{cases} x_1 + 2x_2 + 3x_3 = b_1 \\ 2x_1 + 5x_2 + 3x_3 = b_2 \\ x_1 \quad \quad + 8x_3 = b_3 \end{cases}$$

[2] Determine Conditions on k for the following system to have:

- (a) unique sol
- (b) No solution
- (c) as many solutions

$$\begin{cases} kx + y + z = 1 \\ x + ky + z = 1 \\ x + y + kz = 1 \end{cases}$$

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determine Conditions on k for the following system to have

$$\begin{cases} kx + y + z = 0 \\ x + ky + z = 0 \\ x + y + kz = 0 \end{cases}$$

- (a) a unique solution
- (b) a one-parameter family of solutions
- (c) a two-parameter family of solutions